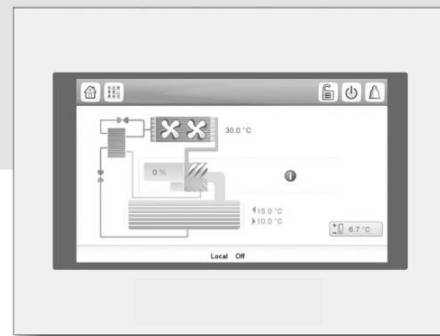




CONTROLS MANUAL



Touch Pilot Control

30XA/XAS/XB/XBP/XW
30XA-ZE/XW-ZE

AquaForce® PUREtec with R-1234ze(E)

CONTENTS

| | |
|--|-----------|
| 1 - SAFETY CONSIDERATIONS | 5 |
| 1.1 - General description | 5 |
| 1.2 - Safety precautions | 5 |
| 2 - CONTROLLER OVERVIEW | 5 |
| 2.1 - General description | 5 |
| 2.2 - Abbreviations | 5 |
| 3 - HARDWARE DESCRIPTION | 6 |
| 3.1 - General description | 6 |
| 3.2 - Electrical box | 6 |
| 3.3 - Connections of the main controller | 6 |
| 3.4 - Power supply to boards | 6 |
| 3.5 - Light emitting diodes on boards | 6 |
| 3.6 - Pressure sensors | 7 |
| 3.7 - Temperature sensors | 7 |
| 3.8 - Actuators | 7 |
| 3.9 - Connections at the user terminal block | 8 |
| 4 - TOUCH PILOT CONTROL INTERFACE | 9 |
| 4.1 - General description | 9 |
| 4.2 - Screens overview | 9 |
| 4.3 - Welcome Screen | 9 |
| 4.4 - Touch Pilot synoptic screen | 9 |
| 4.5 - Start/Stop screen | 10 |
| 4.6 - User Login screen | 10 |
| 4.7 - Language list selection | 11 |
| 4.8 - Main menu | 11 |
| 4.9 - Configuration menu | 12 |
| 4.10 - Override screen | 12 |
| 4.11 - Schedule screen | 12 |
| 5 - WEB CONNECTION | 13 |
| 5.1 - Web interface access | 13 |
| 5.2 - Web browser configuration | 13 |
| 5.3 - Technical documentation access | 13 |
| 6 - TOUCH PILOT INTERFACE DETAILS | 14 |
| 6.1 - Menu structure | 14 |
| 6.2 - Detailed menu description | 15 |
| 6.3 - Alarms menu | 22 |
| 6.4 - Configuration menu | 23 |
| 7 - TOUCH PILOT CONTROL OPERATION | 27 |
| 7.1 - Start/Stop control | 27 |
| 7.2 - Unit stop function | 27 |
| 7.3 - Heating/Cooling selection | 27 |
| 7.4 - Pumps control | 28 |
| 7.5 - Condenser water pump control | 28 |
| 7.6 - Control point | 29 |
| 7.7 - Capacity limitation | 30 |
| 7.8 - Current limitation | 30 |
| 7.9 - Capacity control | 30 |
| 7.10 - Night mode | 31 |
| 7.11 - Head pressure control | 31 |
| 7.12 - Circuit lead/lag selection (multi-circuit units) | 31 |
| 7.13 - Compressor loading sequence (multi-circuit units) | 31 |
| 7.14 - Circuit capacity loading sequence | 31 |
| 7.15 - Energy management module | 33 |
| 7.16 - Master/slave assembly | 33 |
| 7.17 - Heat reclaim option (30XA/30XB) | 33 |
| 7.18 - Variable speed fans (option 17) | 33 |
| 7.19 - Evaporator heater option (30XA/30XB) | 33 |
| 7.20 - Free cooling option (30XA/30XB) | 34 |
| 7.21 - Dry Cooler Free Cooling (30XB) | 34 |
| 7.22 - Dry cooler option (30XW) | 34 |
| 7.23 - Hydronic kit option (30XA/30XB) | 34 |
| 7.24 - 30XA-ZE and 30XW-ZE units (HFO) | 34 |
| 7.25 - High condensing temperature option (30XW) | 34 |
| 7.26 - Maximum condenser leaving water temperature option (30XW) | 34 |
| 7.27 - Time schedule function | 35 |
| 7.28 - Black box function | 35 |
| 7.29 - Trending | 35 |

CONTENTS

| | |
|--|-----------|
| 8 - DIAGNOSTICS – TROUBLESHOOTING | 36 |
| 8.1 - E-mail notifications | 36 |
| 8.2 - Displaying alarms | 36 |
| 8.3 - Current alarms..... | 36 |
| 8.4 - Resetting alarms | 36 |
| 8.5 - Alarm history..... | 36 |
| 8.6 - Alarm codes..... | 37 |

The cover photos are solely for illustration and forms no part of any offer for sale or any sale contract. The manufacturer reserves the right to change the design at any time without notice.

PREFACE

The goal of this document is to give a broad overview of the main functions of the Touch Pilot system used to control:

- 30XAS single-circuit air-cooled chillers,
- 30XA dual-circuit and triple-circuit air-cooled chillers,
- 30XB dual-circuit air-cooled chillers with fixed-speed fan control and 30XBP dual-circuit air-cooled chillers with variable-speed fan control,
- 30XW single-circuit and dual-circuit water-cooled chillers,
- units that come with R-1234ze refrigerant (30XA-ZE air-cooled and 30XW-ZE water-cooled chillers).

Instructions in this manual are given as a guide to good practice in the installation, start-up and operation of the control system. This document does not contain full service procedures for the correct operation of the equipment. The support of a qualified Carrier Service Engineer is strongly recommended to ensure optimal operation of the equipment as well as the optimization of all available functionalities.

Note that this document may refer to optional components and certain functions, options or accessories may not be available for the specific unit. The cover images are solely for illustration and form no part of any offer for sale or any sale contract.

IMPORTANT: All screenshots of the interface provided in this manual include text in English. After changing the language of the system, all labels will be displayed in the language selected by the user.



Please read all instructions prior to proceeding with any work. Pay attention to all safety warnings.

The information provided herein is solely for the purpose of allowing customers to operate and service Carrier-manufactured equipment and it is not to be reproduced, modified or used for any other purpose without the prior consent of Carrier Corporation.

1 - SAFETY CONSIDERATIONS

1.1 - General description

Installation, start-up and servicing of equipment can be hazardous if certain factors particular to the installation are not considered: operating pressures, electrical components, voltages and the installation site (elevated plinths and built-up structures).

Only qualified installation engineers and fully trained technicians are authorised to install and start the equipment. All instructions and recommendations provided in the service guide, installation and operation manuals, as well as on tags and labels fixed to the equipment, components and other accompanying parts supplied separately, must be read, understood and followed. Failure to comply with the instructions provided by the manufacturer may result in injury or product damage.

- **Apply all safety standards and practices.**
- **Wear safety glasses and gloves.**
- **Use the proper tools to move heavy objects.**
- **Move units carefully and set them down gently.**

1.2 - Safety precautions

Only personnel qualified in accordance with IEC (International Electrotechnical Commission) recommendations may be permitted access to electrical components. It is particularly recommended that all sources of electricity to the unit should be shut off before any work is begun. Shut off the main power supply at the main circuit breaker or isolator.

CAUTION: The equipment uses and emits electromagnetic signals. Tests have shown that the equipment conforms to all applicable codes with respect to electromagnetic compatibility.

RISK OF ELECTROCUTION: Even when the main circuit breaker or isolator is switched off, specific circuits may still be energised as they may be connected to a separate power source.

RISK OF BURNS: Electrical currents may cause components to get hot. Handle power cable, electrical cables and conduits, terminal box covers and motor frames with great care.

IMPORTANT: Some specific safety precautions should be taken in case of HFO units.

For more information about handling the equipment safely, please refer to the IOM Unit documentation (Installation, Operation and Maintenance instructions).

2 - CONTROLLER OVERVIEW

2.1 - General description

The Touch Pilot system controls the start-up of the compressors needed to maintain the desired heat exchanger entering and leaving water temperature. The controller manages the operation of the fans in order to maintain the correct condensing pressure in each circuit. Touch Pilot constantly monitors safety devices that protect the unit against failure and guarantee its optimal functioning.

The control system can operate in three independent modes:

- **Local mode:** The unit is controlled by commands from the user interface.
- **Remote mode:** The unit is controlled by dry contacts.
- **Network mode:** The unit is controlled by network commands (CCN or BACnet). Data communication cable is used to connect the unit to the CCN communication bus.

The operating mode can be selected with the Start/Stop button (see also section 4.5). When the Touch Pilot system operates autonomously (Local or Remote), it retains all of its control capabilities but does not offer any of the features of the Network. The Network emergency stop command stops the unit regardless of its active operating type.

2.2 - Abbreviations

In this manual, the refrigeration circuits are called circuit A, circuit B and circuit C.

| | |
|----------------|---|
| CCN | Carrier Comfort Network |
| DCFC | Dry Cooler Free Cooling |
| EMM | Energy Management Module |
| EXV | Electronic Expansion Valve |
| LED | Light Emitting Diode |
| LEN | Sensor Bus (internal communication bus linking the basic board to slave boards) |
| OAT | Outdoor Air Temperature |
| Network mode | Operating type: Network |
| Local-Off | Operating type: Local Off |
| Local-On | Operating type: Local On mode |
| Local-Schedule | Operating type: Local On following a time schedule |
| Master mode | Operating type: master unit (master/slave assembly) |
| Remote mode | Operating type: by remote contacts |
| VFD | Variable Frequency Drive |

3 - HARDWARE DESCRIPTION

3.1 - General description

Each circuit is by default fitted with one SIOB board used to manage all inputs and outputs of the controller.

TCPM board is used to control the operation of screw compressors and AUX1 board is used for fans control (one AUX1 per each circuit). Please note that the first AUX1 board may also include the output used to control the customer variable speed pump for single-circuit units (see also section 7.4.3).

Options such as energy management, heat reclaim, free cooling require additional SIOB boards to be installed. Additionally, chillers fitted with a dry cooler have one extra AUX1 board used to control the optional dry cooler (the board included in the dry cooler).

NOTE: There are two types of dry coolers available, i.e. dry cooler (condenser) used for 30XW water-cooled units and free cooling dry cooler for 30XB air-cooled units.

All boards communicate via an internal LEN bus. The main board continuously monitors the information received from various pressure and temperature probes and accordingly starts the program that controls the unit.

The unit is equipped with the Touch Pilot user interface (5-inch colour LCD touch screen).

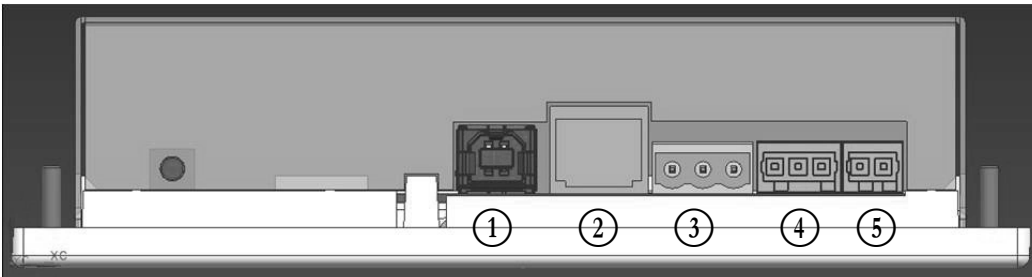
3.2 - Electrical box

The electrical box includes all boards controlling the unit and the user interface.



3.3 - Connections of the main controller

Connections are located on the bottom side of the main controller.



Legend

1. USB connector
2. Ethernet connector
3. CCN connector
4. LEN connector
5. Power supply connector (24 VAC)

3.4 - Power supply to boards

All boards are supplied from a common 24 VAC supply referred to earth.

CAUTION: Maintain correct polarity when connecting the power supply to the boards, otherwise the boards may be damaged.

In the event of a power supply interrupt, the unit restarts automatically without the need for an external command. However, any faults active when the supply is interrupted are saved and may in certain cases prevent a given circuit or the unit from restarting.

3.5 - Light emitting diodes on boards

All boards continuously check and indicate the proper operation of their electronic circuits. A light emitting diode (LED) lights on each board when it is operating properly.

- The red LED flashing for a two-second period on the SIOB board indicates correct operation. A different rate indicates a board or a software failure.
- The green LED flashes continuously on all boards to show that the board is communicating correctly over its internal bus. If the green LED is not flashing, this indicates a LEN bus wiring problem.

3 - HARDWARE DESCRIPTION

3.6 - Pressure sensors

Two types of electronic sensors (high and low pressure) are used to measure various pressures in each circuit.

These electronic sensors deliver 0 to 5 VDC. The sensors are connected to the SIOB board.

■ Discharge pressure sensors (high pressure type)

These sensors measure the discharge pressure in each circuit. They are used to control head pressure or high pressure load shedding. Discharge pressure sensors are mounted on the discharge line piping of each circuit.

■ Suction pressure sensors (low pressure type)

These sensors measure the suction pressure in each circuit. They are used for EXV control. Suction pressure sensors are located on the suction piping of each circuit.

■ Oil pressure sensors (high pressure type)

These sensors measure the oil pressure of each compressor. Oil pressure sensors are located at the oil port of the compressor. The economizer pressure is subtracted from this value to arrive at the differential oil pressure.

■ Economizer pressure sensors (high pressure type)

These sensors measure the intermediate pressure between high and low pressure. They are used to control the economizer performance.

■ Heat reclaim condenser outlet pressure sensors (optional)

These sensors (for air-cooled units with heat reclaim option) permit control of the load in the heat reclaim mode (see also section 7.17).

3.7 - Temperature sensors

Temperature sensors constantly measure the temperature of various components of the unit, ensuring the correct operation of the system.

■ Evaporator entering and leaving water temperature sensors

The evaporator entering and leaving water temperature sensors are installed in the entering and leaving side water box. They are used for capacity control and safety purposes.

■ Condenser entering and leaving water temperature sensors

These sensors measure the entering and leaving water temperatures in water-cooled units or air-cooled units with the heat reclaim option.

■ Suction gas temperature sensor

This sensor is used to control the suction gas temperature. It is located at the suction line of each compressor.

■ Discharge gas temperature sensor

This sensor is used to control the discharge gas temperature, and permits control of the discharge superheat temperature. It is located at the discharge line of the compressor.

■ Motor temperature sensor

This sensor is used to control the motor temperature of each compressor.

■ Oil temperature sensor

This sensor is used to control the oil temperature of each compressor.

■ Temperature setpoint reset sensor

This 4-20 mA sensor can be installed remotely from the unit. It is used to reset the setpoint on the unit.

■ Outdoor temperature sensor

This sensor is mounted on the control box of air-cooled units. Outdoor temperature sensor is used for start-up, setpoint temperature reset and frost protection control.

■ Master/slave water sensor (optional)

The water temperature sensor is used for master/slave assembly control.

3.8 - Actuators

■ Evaporator pumps

The controller can regulate one or two evaporator pumps and takes care of the automatic changeover between these pumps (see also section 7.4).

■ Condenser pump

In water-cooled units the controller can regulate one condenser pump.

■ Electronic expansion valve

The electronic expansion valve (EXV) is used to adjust the refrigerant flow to changes in the operating conditions of the machine. To adjust the refrigerant flow, a piston moves constantly up or down to vary the cross-section of the refrigerant path. This piston is driven by an electronically controlled linear stepper motor. The high degree of accuracy with which the piston is positioned provides precise control of the refrigerant flow.

■ Water flow switch

The water flow switch configuration allows for the automatic control of the minimum water flow setpoint of the water flow switch. The configuration depends on the unit size and is made automatically at the start-up. If the measured water flow rate in the water loop is lower than the configured flow rate, the alarm condition shuts off the unit.

3 - HARDWARE DESCRIPTION

3.9 - Connections at the user terminal block

Connections available at the user terminal block may vary depending on the selected options.

3.9.1 - General description

Some contacts can be accessed only when the unit operates in Remote mode.

The following table summarises the connections at the user terminal block.

| Terminal block connections | | | | |
|---|--------------------|--------------|-----------|---|
| Description | Board | Input/Output | Connector | Remarks |
| On/Off switch | SIOB, circuit A | DI-01 | J1 | Used for the unit on/off control if the unit is in Remote mode |
| Second setpoint switch | SIOB, circuit A | DI-02 | J1 | The contact is taken into consideration if the unit is in Remote mode |
| Demand limit switch 1 | SIOB, circuit A | DI-03 | J1 | Used to control demand limit. See section 7.7 |
| Heat cool select status | SIOB, circuit A | DI-04 | J1 | Used to select heat cool mode |
| Condenser flow status (30XW only) | SIOB, circuit A | DI-08 | J1 | Used to control the condenser status |
| Setpoint reset control | SIOB, circuit A | AI-10 | J9 | Allows the customer to reset the currently selected setpoint |
| Alarm relay | SIOB, circuit A | DO-05 | J23 | Indicates alarms |
| Running relay | SIOB, circuit A | DO-06 | J22 | Indicates if the unit is ready to start or operating |
| Variable speed pump command (dual-circuit 30XW units and 30XB units with option 17) | SIOB, circuit B | AO-01 | J10 | Used to command the customer variable speed cooler pump (0-10V). See section 7.4.3 |
| Variable speed pump command (single-circuit 30XW units) | AUX1 #1 | AO | J5 | Used to command the customer variable speed cooler pump (0-10V). See section 7.4.3 |
| Optional | | | | |
| Occupancy override | SIOB, EMM | DI-01 | J1 | Enables to switch between occupied (closed contact) and unoccupied mode (open contact) |
| Demand limit switch 2 | SIOB, EMM | DI-02 | J1 | Used to control demand limit. See section 7.7 |
| Customer interlock | SIOB, EMM | DI-03 | J1 | Used for the customer safety loops |
| Ice done contact | SIOB, EMM | DI-04 | J1 | Used to control the setpoint according to the occupancy schedule |
| Capacity limit control | SIOB, EMM | AI-10 | J9 | Used for capacity limitation |
| Chiller partially shutdown | SIOB, EMM | DO-05 | J23 | Indicates the shutdown of one of the circuits |
| Chiller shutdown | SIOB, EMM | DO-06 | J22 | Indicates the unit shutdown |
| Chiller capacity running output (0 to 10 V) | SIOB, EMM | AO-01 | J10 | Reports the capacity percentage of the unit |
| Heat reclaim condenser flow status (air-cooled units) | SIOB, Heat reclaim | DI-01 | J1 | Used to verify the water flow on the condenser side |
| Heat reclaim enable switch (air-cooled units) | SIOB, Heat reclaim | DI-02 | J1 | Used to switch between air-condenser (open contact) and water condenser (closed contact) in Remote mode |
| Free cooling disable switch (air-cooled units) | SIOB, Free cooling | DI-01 | J1 | Used to control free cooling when the unit is in Remote mode |

3.9.2 - Volt-free contact on/off/cooling/heating

If the unit operates in Remote mode, on/off contacts and heating/cooling contacts operate as follows:

| Without multiplexing | | | |
|--------------------------------|------|---------|---------|
| | Off | Cooling | Heating |
| On/Off contact | open | closed | closed |
| Cooling/heating contact | - | open | closed |

| With multiplexing | | | | |
|--------------------------------|------|---------|---------|--------|
| | Off | Cooling | Heating | Auto |
| On/Off contact | open | closed | closed | open |
| Cooling/heating contact | open | open | closed | closed |

Legend

1. Off: Unit is stopped
2. Cooling: Unit is allowed to start in Cooling
3. Heating: Unit is allowed to start in Heating
4. Auto: Unit can run in Cooling or Heating in accordance with the changeover values.

3.9.3 - Volt-free setpoint selection contact

This dry contact input is used to switch between setpoints. It is active only when the control is in Remote mode.

| | Cooling | | Heating | |
|-----------------------------------|------------|------------|------------|------------|
| | Setpoint 1 | Setpoint 2 | Setpoint 1 | Setpoint 2 |
| Setpoint selection contact | open | closed | open | closed |

3.9.4 - Volt-free demand limit selection contact

Up to two dry contacts can be used to limit unit capacity. Note that the second contact is available for units with the energy management module.

Capacity limitation with two contacts is as follows:

| | 100% | Limit 1 | Limit 2 | Limit 3 |
|-------------------------------|------|---------|---------|---------|
| Demand limit 1 contact | open | closed | open | closed |
| Demand limit 2 contact | open | open | closed | closed |

The limits are defined in the SETPOINT menu.

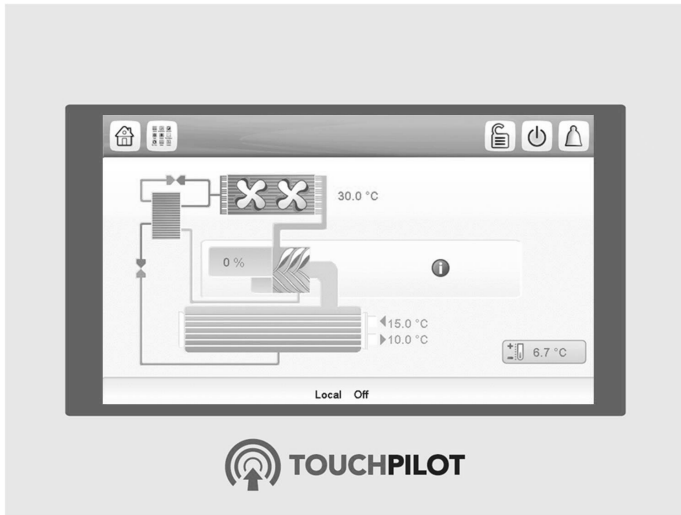
4 - TOUCH PILOT CONTROL INTERFACE

4.1 - General description

Touch Pilot includes the 5 in. touch screen allowing for easy system control. Navigation through the Touch Pilot control is either using the touch screen interface or by connecting to the web interface. It is recommended to use a pen for the navigation via the touch screen.

The navigation menus are the same for both connection methods (Touch Pilot user interface and web browser). Only two web connections are authorised at the same time.

NOTE: Some functionalities are unavailable when using the web browser interface.



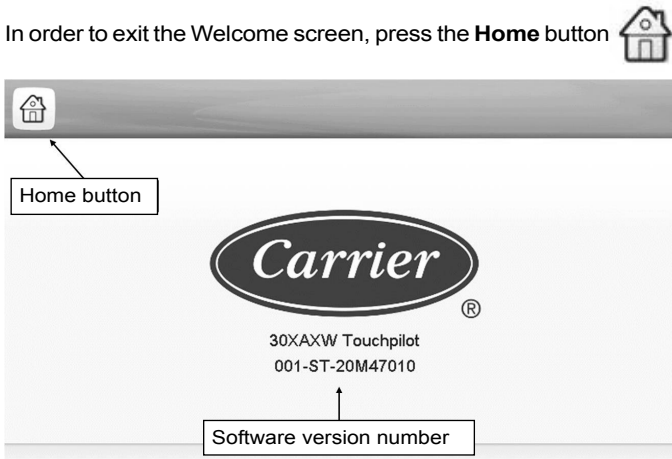
4.2 - Screens overview

The Touch Pilot control interface includes the following screens:

- Welcome screen
- Synoptic screen
- Operating mode selection screen
- Data/configuration screens
- Password entry and language selection screen
- Alarms screen
- Parameter modification screen
- Time schedule screen
- Trending visualisation screen

4.3 - Welcome Screen

The Welcome screen is the first screen shown after starting the Touch Pilot user interface. It displays the application name as well as the current software version number.



4.4 - Touch Pilot synoptic screen

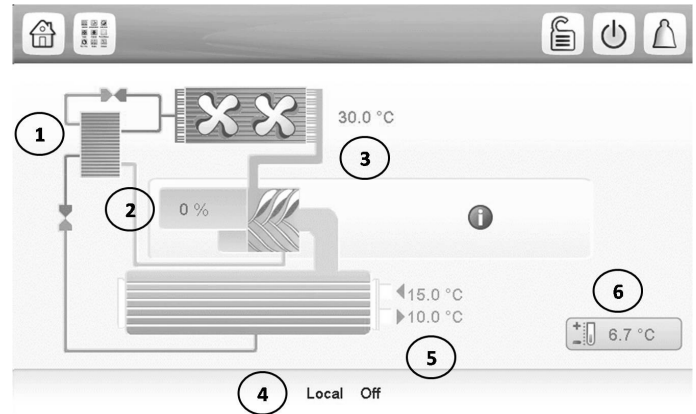
The Synoptic screen provides an overview of the system control, allowing the user to monitor the vapour-refrigeration cycle. The diagram indicates the current status of the unit, giving information on the unit capacity, the status of condenser and evaporator pump, and the pre-defined setpoint parameter.

All unit functions can be accessed by pressing

the **Main menu** button

The bell located in the upper-right part of the screen lights when any fault is detected (see also section 8.2).

By default, the parameters are presented in metric units. For more information on how to change the system of measurement, see section 4.6.



Legend

1. Economizer
2. Unit capacity percentage
3. Outdoor air temperature
4. Status screen message
5. Evaporator inlet and outlet water temperature
6. Setpoint

NOTE: The synoptic screen display may vary depending on pumps configuration.

Information message box

The information displayed in the status bar at the bottom of the screen includes relevant messages regarding the current user action.

All screens presented further in this manual may display the following messages:


| MESSAGE | STATUS |
|--------------------------------|--|
| COMMUNICATION FAILURE! | Equipment controller did not respond while reading the table content. |
| ACCESS DENIED! | Equipment controller denies access to one of the table data blocks. |
| LIMIT EXCEEDED! | The value entered exceeds the table limits. |
| Save changes? | Modifications have been made. The exit must be confirmed by pressing Save or Cancel. |
| HIGHER FORCE IN EFFECT! | Equipment controller rejects Force or Auto command. |

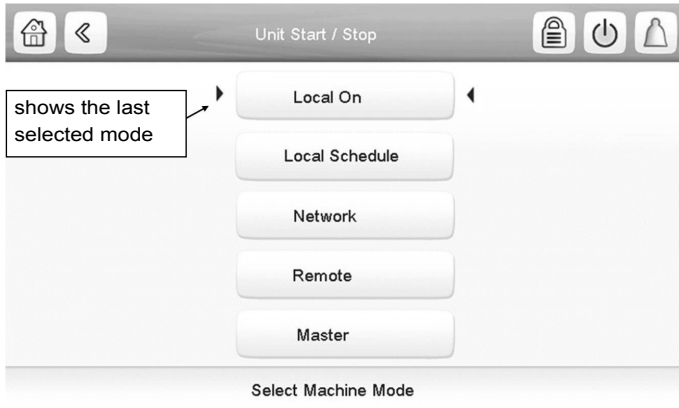
4 - TOUCH PILOT CONTROL INTERFACE

4.5 - Start/Stop screen

The Start/Stop screen allows users to select the operating mode of the unit.

4.5.1 - Unit start-up


With the unit in the Local off mode, press the **Start/Stop** button  to display the list of operating modes and select the required mode.




NOTE: When entering the menu, please note that the currently selected item corresponds to the last running operating type.

| | |
|-----------------------|--|
| Local On | Local On: The unit is in the local control mode and allowed to start. |
| Local Schedule | Local Schedule: The unit is in the local control mode and allowed to start if the period is occupied. |
| Network | Network: The unit is controlled by network commands and allowed to start if the period is occupied. |
| Remote | Remote: The unit is controlled by external commands and allowed to start if the period is occupied. |
| Master | Master: The unit operates as the master in the master/slave assembly and allowed to start if the period is occupied. |

4.5.2 - Unit stop

In order to stop the unit, press the **Start/Stop** button .




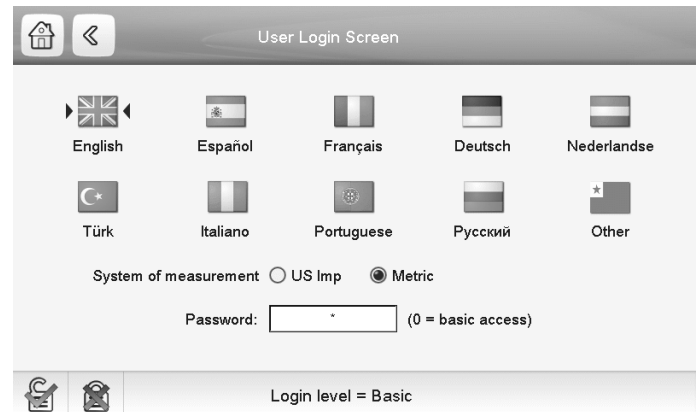
Confirm the unit shutdown by pressing **Confirm Stop** or return to the previous screen by pressing the **Back** button .

Once the unit has been stopped, the Synoptic screen will be displayed (see also section 4.4).

4.6 - User Login screen



The User Login screen allows the user to select the language of the controller, change the system of measurement (imperial or metric) and enter a password to gain access to more control options (default password = 11).

The User Login screen can be accessed by pressing the **Log** button  in the upper-right corner of the screen (see also section 4.4).



Legend

1. Cursor indicating the selected language
2. Logged-in button
3. Logged-off button
4. System of measurement selection: Metric/Imperial
5. Password dialog box

Once all the changes have been made, press  to save or  to cancel changes.

NOTE: Password validation is effective only after pressing the Logged-in button.

Security access settings

- User-level security ensures that only authorised users are allowed to modify critical unit parameters.
- Only logged-in users are allowed to access the Configuration menu.
- It is strongly recommended to change the default password of the user interface to exclude the possibility of changing any parameters by an unqualified person.
- Only people qualified to manage the unit should be familiarized with the password.

User password can be modified in the User Configuration menu.

To change your password

1. Go to the Main Menu.
2. Navigate to the Configuration menu (logged-in users only) and select User Configuration (USERCONF).
3. Select the User Password box and provide your new password.
4. Press OK. The User Configuration screen appears.
5. Press the Save button to save your changes or the Cancel button to exit the screen without making modifications.

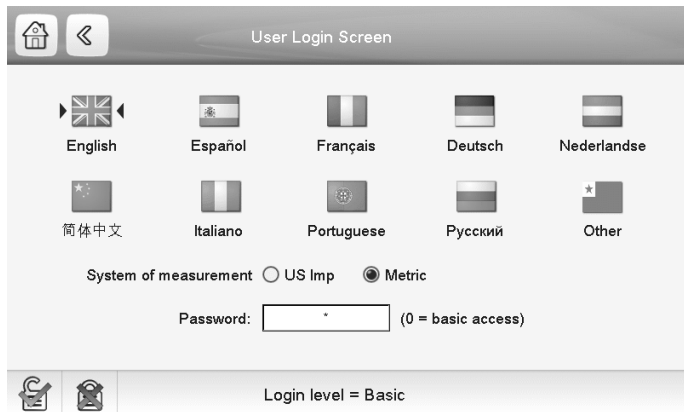
4 - TOUCH PILOT CONTROL INTERFACE

4.7 - Language list selection

The control provides two different language lists which means that languages displayed in the User Login screen may vary depending on user preferences ("Language list" parameter in USERCONF - User Configuration).

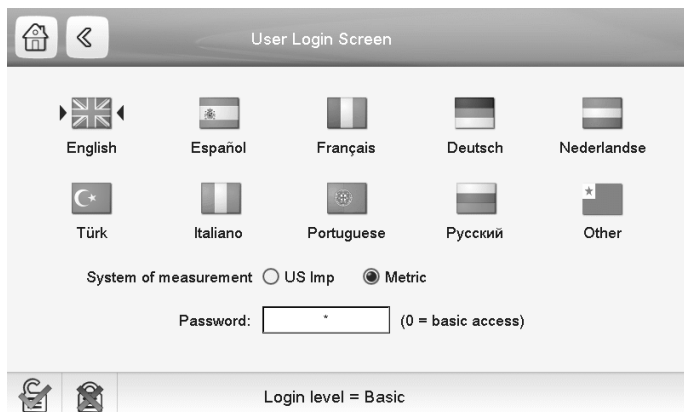
Language list (in USERCONF menu) set to "0":

English, Spanish, French, German, Dutch, Chinese, Italian, Portuguese, Russian, and "other" (custom language).



Language list (in USERCONF menu) set to "1":

English, Spanish, French, German, Dutch, Turkish, Italian, Portuguese, Russian, and "other" (custom language).




Custom language

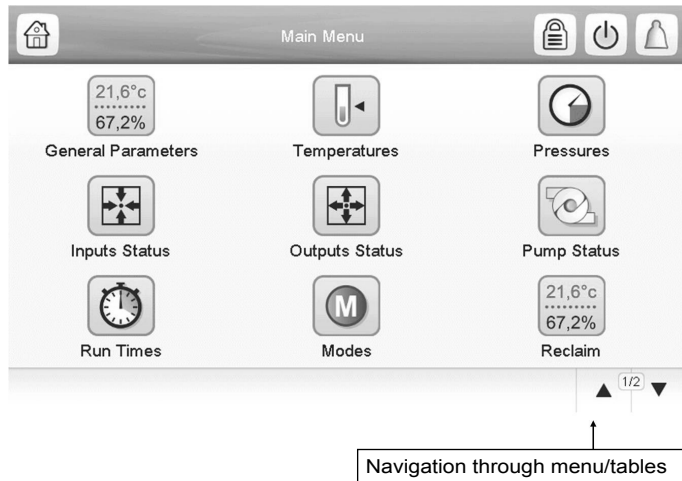
The control system allows users to add new languages to the control. To learn more about language customization, please contact your local Carrier service representative.


NOTE: Custom languages can be uploaded only by Carrier service technicians.

4.8 - Main menu

The Main menu provides access to the main control parameters, including general parameters, inputs and outputs status, etc.


In order to access the menu, press the **Main menu** button  located in the upper-left part of the Synoptic screen (see also section 4.4).

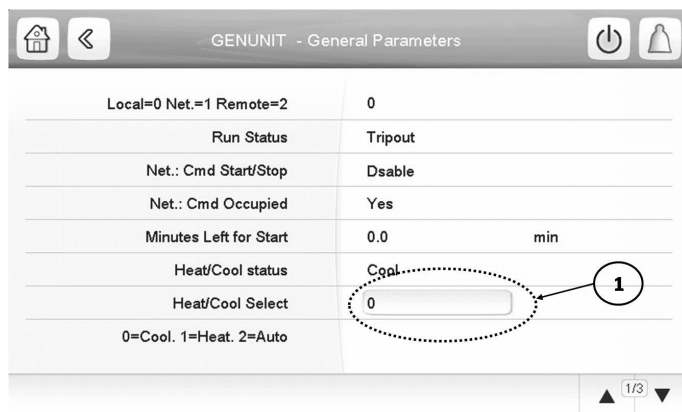


Specific unit parameters table/menu can be accessed by pressing the icon corresponding to the desired category. In order to go back to the Synoptic screen, press .

4.8.1 - General parameters screen

The General parameters screen provides access to a set of general unit parameters.

To access the General parameters screen, go to the Main menu and select **General Parameters** .



Legend

1. Forceable point

Press the **Up/Down** buttons  to navigate between the screens.

4.8.2 - Parameter modification

When the user selects the parameter to be modified, the following screen is displayed.

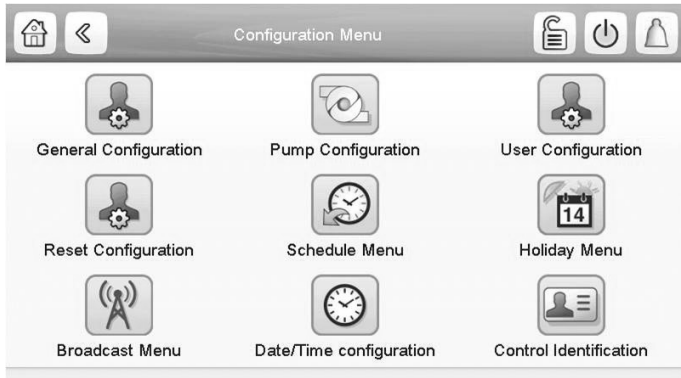


Press **OK** to save or **EXIT** to cancel the modification.

4 - TOUCH PILOT CONTROL INTERFACE

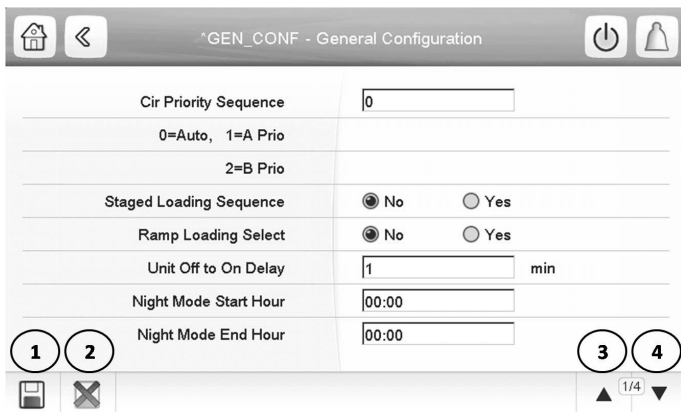
4.9 - Configuration menu

The Configuration menu gives access to a number of user-modifiable parameters such as pump configuration, schedule menu, etc.



General configuration screen

To access the General configuration screen, go to the Configuration menu and select General Configuration





Legend

- 1. Save
- 2. Cancel
- 3. Previous page
- 4. Next page

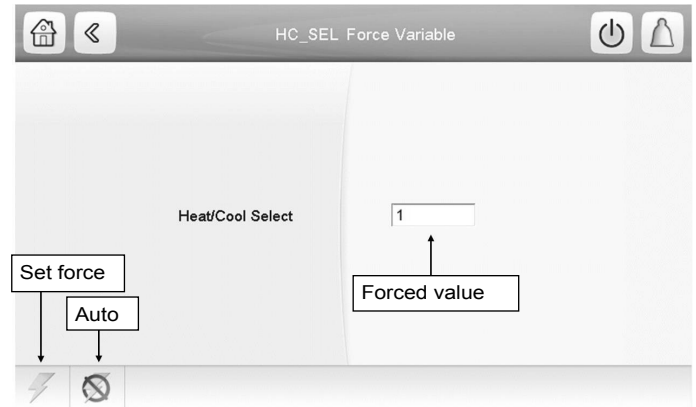
Press the field corresponding to the parameter to be modified and introduce all the necessary changes.

Press the **Up/Down** buttons   to navigate between the screens.

Once all the necessary modifications have been made, press  to confirm or  to cancel changes.

4.10 - Override screen


The override screen provides the option to issue the command overriding the current operation of the unit. To access the override screen, press the forceable point of the data screen.



Press  to set or  to remove the forced point.

4.11 - Schedule screen

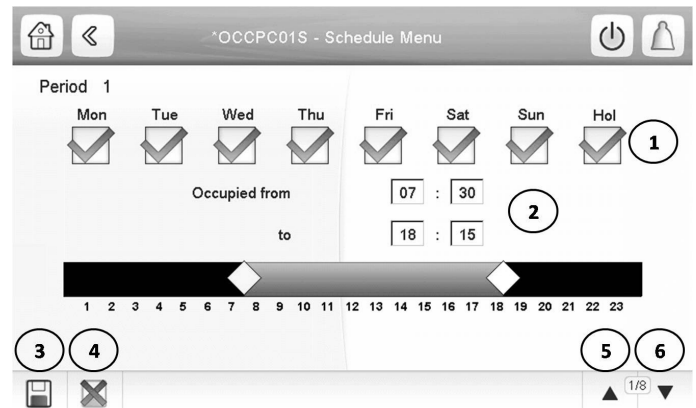
The control incorporates two time schedules, where the first one (OCCPC01S) is used for controlling the unit start/stop, whereas the second one (OCCPC02S) is used for controlling the dual setpoint.

To access the Schedule screen, go to the Configuration menu and select **Schedule Menu** .

Set the time schedule and the selected period will be presented in the form of the green band on the timeline.

Press  to confirm or  to cancel changes.

Each program is in unoccupied mode unless a schedule time period is active. If two periods overlap and are both active on the same day, the occupied mode takes priority over the unoccupied period.



Legend

- 1. Selection of the applicable days for the time schedule
- 2. Modification of the period: start time and end time
- 3. Save
- 4. Cancel
- 5. Previous time period
- 6. Next time period

5 - WEB CONNECTION

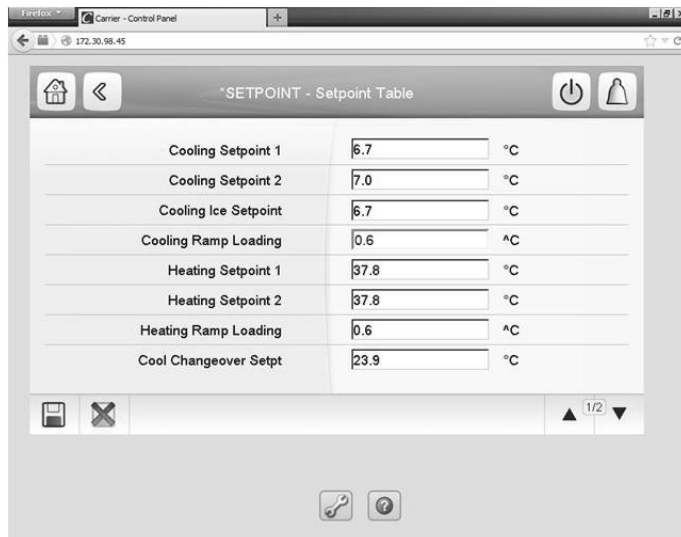
The Touch Pilot system control can be accessed via a web browser (Internet Explorer, Mozilla Firefox, etc.). Connection is from a PC using a web browser with Java.

CAUTION: PCD controllers accessible via the Internet must be protected by firewall and VPN connection.

5.1 - Web interface access

In order to access Touch Pilot, enter the IP address of the unit in the address bar of the web browser.

Unit default address: 169.254.0.1.



NOTE: Only two web connections may be authorised at the same time.

5.2 - Web browser configuration


Minimum web browser configuration:

- Internet Explorer (version 8 or higher) or Mozilla Firefox (version 26 or higher). In the advanced connection options add the unit IP address to the exceptions list. Do not use a proxy server.
- Java platform (version 6 or higher). In the control panel, clear the Keep temporary files on my computer checkbox and use a direct connection.

NOTE: Two users can be connected simultaneously with no priority between them. The last modification is taken into account.

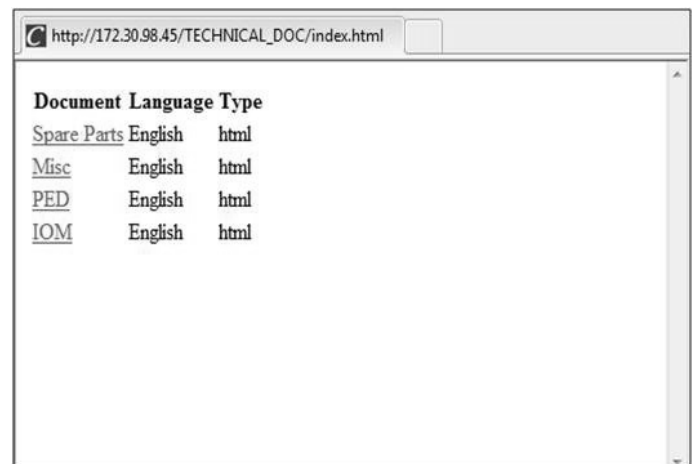
5.3 - Technical documentation access

When the Touch Pilot control is used via a PC web browser, the controller allows the user to access the technical documentation for the product.

Press the **Technical document** button  to access a list of documents related to the unit and its components.

Technical documentation includes the following documents:

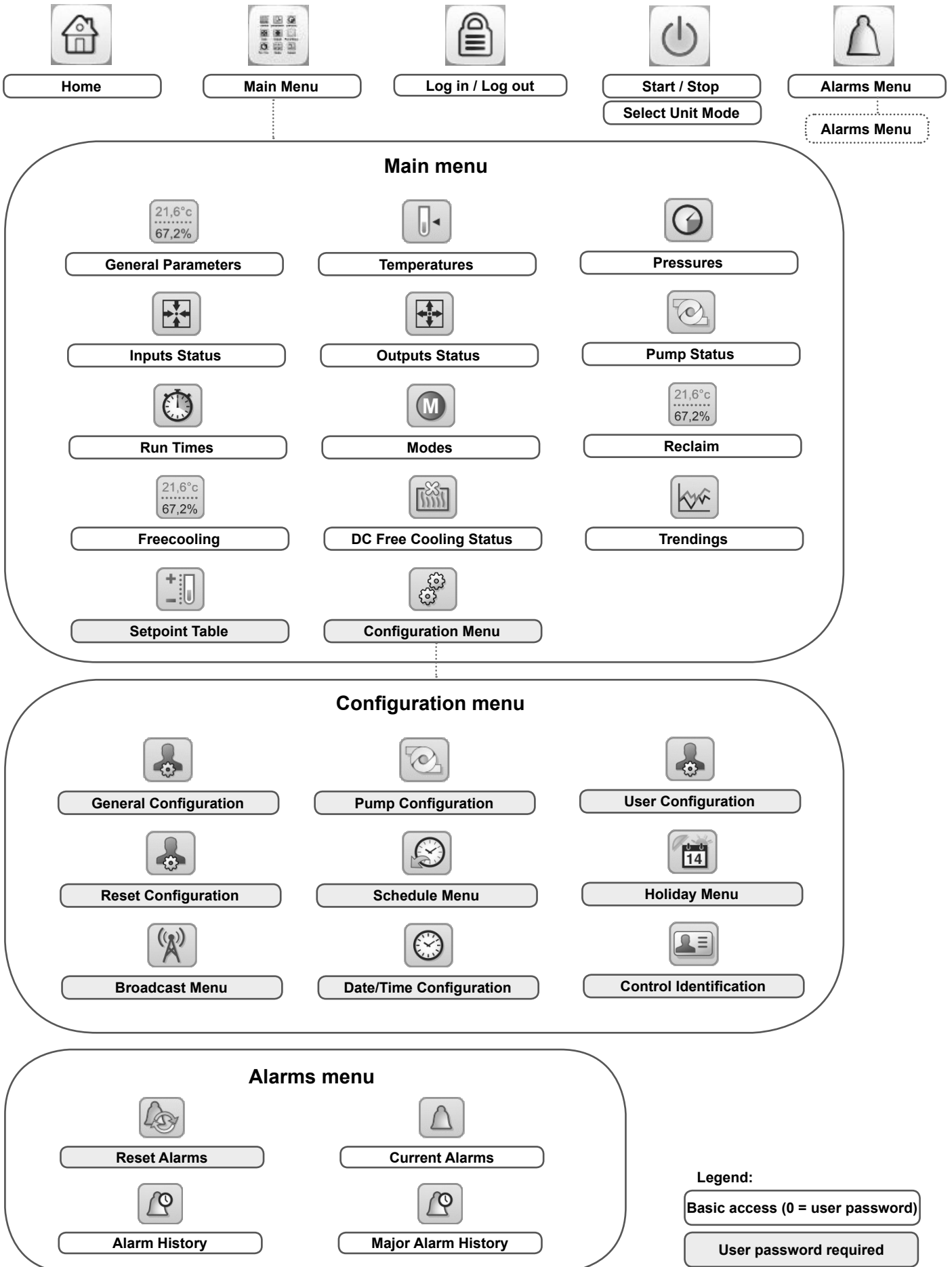
- Spare parts documentation: The list of spare parts included in the unit with reference, description and drafting.
- Misc: Documents such as regulation algorithm, electrical plans, dimension plans, unit certificates.
- PED: Pressure Equipment Directive.
- IOM: Installation operation and maintenance manual, controls installation/maintenance manual.



IMPORTANT: Please save all data (documents, drawings, diagrams, etc.), for example, on your computer. If display memory is erased or the display is replaced, all documents will be lost. Make sure that all documents are stored and may be accessed at any time.

6 - TOUCH PILOT INTERFACE DETAILS

6.1 - Menu structure



6 - TOUCH PILOT INTERFACE DETAILS

6.2 - Detailed menu description

| Icon | Displayed text* | Description | Associated table |
|---|------------------------|--------------------------------|------------------|
|  | General Parameters | General parameters | GENUNIT |
|  | Temperatures | Temperatures | TEMP |
|  | Pressures | Pressures | PRESSURE |
|  | Inputs Status | Inputs status | INPUTS |
|  | Outputs Status | Outputs status | OUTPUTS |
|  | Pump Status | Pump status | PUMPSTAT |
|  | Run Times | Run times | RUNTIME |
|  | Modes | Modes | MODES |
|  | Reclaim | Reclaim | RECLAIM |
|  | DC Free Cooling Status | Dry Cooler Free Cooling status | DCFC_STA |
|  | Freecooling | Free cooling | FREECOOL |
|  | Setpoint Table | Setpoint table | SETPOINT |
|  | Trendings | Trendings | TRENDING |
|  | Configuration Menu | Configuration menu | CONFIG |

* Depends on the selected language (English by default).



GENUNIT – General parameters

| No. | Status | Unit | Displayed text* | Description |
|-----|----------|------|-------------------------|---|
| 1 | 0 to 3 | - | Local=0 Net.=1 Remote=2 | Operating mode: 0 = Local 1 = Network 2 = Remote |
| 2 | - | - | Run Status | Unit running status: Off, Stopping, Delay, Running, Ready, Override, Tripout, Test, Runtest |
| 3 | 0 to 1 | - | Net.: Cmd Start/Stop | Unit start/stop via Network |
| 4 | 0 to 1 | - | Net.: Cmd Occupied | Unit time schedule via Network |
| 5 | - | min | Minutes Left for Start | Minutes before the unit start-up |
| 6 | - | - | Heat/Cool status | Heating/cooling status |
| 7 | 0 to 2 | - | Heat/Cool Select | Heating/cooling selection |
| 8 | - | - | 0=Cool. 1=Heat. 2=Auto | 0 = Cooling 1 = Heating 2 = Automatic heating/cooling control |
| 9 | 0 to 2 | - | Setpoint Select | Setpoint selection |
| 10 | - | - | 0=Auto. 1=Spt1. 2=Spt2 | 0 = Automatic setpoint selection 1 = Setpoint 1 2 = Setpoint 2 |
| 11 | 0 to 1 | - | Setpoint Occupied? | Setpoint status |
| 12 | 0 to 100 | % | Percent Total Capacity | Total unit capacity |

6 - TOUCH PILOT INTERFACE DETAILS

21,6°C
.....
67,2%

GENUNIT – General parameters (continued)

| No. | Status | Unit | Displayed text* | Description |
|-----|----------|------|-------------------------|---------------------------------|
| 13 | - | A | Actual Chiller Current | Actual chiller current |
| 14 | 0 to 200 | A | Chiller Current Limit | Chiller current limit |
| 15 | - | °C | Current Setpoint | Current setpoint value |
| 16 | - | - | Control Point | Control point |
| 17 | 0 to 1 | - | Emergency Stop | Emergency stop |
| 18 | 0 to 100 | % | Active Demand Limit Val | Active demand limit value |
| 19 | 0 to 100 | % | Actual Capacity cir A | Circuit A running capacity in % |
| 20 | 0 to 100 | % | Actual Capacity cir B | Circuit B running capacity in % |
| 21 | 0 to 100 | % | Actual Capacity cir C | Circuit C running capacity in % |

* Depends on the selected language (English by default)



TEMP – Temperatures

| No. | Status | Unit | Displayed text* | Description |
|-----|--------|------|--------------------------|--|
| 1 | - | °C | Cooler Entering Fluid | Evaporator entering water temperature |
| 2 | - | °C | Cooler Leaving Fluid | Evaporator leaving water temperature |
| 3 | - | °C | Condenser Entering Fluid | Condenser entering water temperature |
| 4 | - | °C | Condenser Leaving Fluid | Condenser leaving water temperature |
| 5 | - | °C | Saturated Cond Tmp cir A | Saturated condensing temperature, circuit A |
| 6 | - | °C | Saturated Suction Temp A | Saturated suction temperature, circuit A |
| 7 | - | °C | Compressor Suction Tmp A | Compressor suction temperature, circuit A |
| 8 | - | °C | Discharge Gas Temp cir A | Discharge gas temperature, circuit A |
| 9 | - | °C | Motor Temperature cir A | Motor temperature, circuit A |
| 10 | - | °C | Saturated Cond Tmp cir B | Saturated condensing temperature, circuit B |
| 11 | - | °C | Saturated Suction Temp B | Saturated suction temperature, circuit B |
| 12 | - | °C | Compressor Suction Tmp B | Compressor suction temperature, circuit B |
| 13 | - | °C | Discharge Gas Temp cir B | Discharge gas temperature, circuit B |
| 14 | - | °C | Motor Temperature cir B | Motor temperature, circuit B |
| 15 | - | °C | Saturated Cond Tmp cir C | Saturated condensing temperature, circuit C |
| 16 | - | °C | Saturated Suction Temp C | Saturated suction temperature, circuit C |
| 17 | - | °C | Compressor Suction Tmp C | Compressor suction temperature, circuit C |
| 18 | - | °C | Discharge Gas Temp cir C | Discharge gas temperature, circuit C |
| 19 | - | °C | Motor Temperature cir C | Motor temperature, circuit C |
| 20 | - | °C | Optional Space Temp | Optional space temperature |
| 21 | - | °C | CHWS Temperature | Master/slave common water temperature |
| 22 | - | °C | CHWS Heat Temp | Master/Slave common heat fluid temperature (available depending on unit configuration) |
| 23 | - | °C | External Temperature | External temperature |
| 24 | - | °C | Cooler Heater Temp | Evaporator heater temperature |
| 25 | - | °C | Circuit C Heater Temp | Heater temperature, circuit C |
| 26 | - | °C | Economizer Gas Temp A | Economizer gas temperature, circuit A |
| 27 | - | °C | Economizer Gas Temp B | Economizer gas temperature, circuit B |
| 28 | - | °C | Economizer Gas Temp C | Economizer gas temperature, circuit C |
| 29 | - | °C | Dry Cool Leav Water Tmp | Dry Cooler Leaving Water Temperature (units fitted with a dry cooler) |

* Depends on the selected language (English by default).



PRESSURE – Pressures

| No. | Status | Unit | Displayed text* | Description |
|-----|--------|------|--------------------------|------------------------------------|
| 1 | - | kPa | Discharge Pressure A | Discharge pressure, circuit A |
| 2 | - | kPa | Main Suction Pressure A | Suction pressure, circuit A |
| 3 | - | kPa | Oil Pressure A | Oil pressure, circuit A |
| 4 | - | kPa | Oil Pressure DifferenceA | Oil pressure difference, circuit A |
| 5 | - | kPa | Economizer Pressure A | Economizer pressure, circuit A |
| 6 | - | kPa | Discharge Pressure B | Discharge pressure, circuit B |
| 7 | - | kPa | Main Suction Pressure B | Suction pressure, circuit B |

6 - TOUCH PILOT INTERFACE DETAILS



PRESSURE – Pressures (continued)

| No. | Status | Unit | Displayed text* | Description |
|-----|--------|------|--------------------------|------------------------------------|
| 8 | - | kPa | Oil Pressure B | Oil pressure, circuit B |
| 9 | - | kPa | Oil Pressure DifferenceB | Oil pressure difference, circuit B |
| 10 | - | kPa | Economizer Pressure B | Economizer pressure, circuit B |
| 11 | - | kPa | Discharge Pressure C | Discharge pressure, circuit C |
| 12 | - | kPa | Main Suction Pressure C | Suction pressure, circuit C |
| 13 | - | kPa | Oil Pressure C | Oil pressure, circuit C |
| 14 | - | kPa | Oil Pressure DifferenceC | Oil pressure difference, circuit C |
| 15 | - | kPa | Economizer Pressure C | Economizer pressure, circuit C |

* Depends on the selected language (English by default)



INPUTS – Inputs status

| No. | Status | Unit | Displayed text* | Description |
|-----|------------|------|--------------------------|---|
| 1 | open/close | - | Remote On/Off Switch | Remote On/Off switch |
| 2 | open/close | - | Remote HeatCool Switch | Remote heating/cooling selection switch |
| 3 | open/close | - | Remote Reclaim Switch | Remote reclaim switch |
| 4 | open/close | - | Free Cooling Disable Sw | Free cooling disable switch |
| 5 | open/close | - | Remote Setpoint Switch | Setpoint selection switch |
| 6 | open/close | - | Limit Switch 1 | Demand limit switch 1 |
| 7 | open/close | - | Limit Switch 2 | Demand limit switch 2 |
| 8 | open/close | - | Oil Level Input A | Oil level input, circuit A |
| 9 | open/close | - | Oil Level Input B | Oil level input, circuit B |
| 10 | open/close | - | Oil Level Input C | Oil level input, circuit C |
| 11 | - | A | Motor Current A | Motor current, circuit A |
| 12 | - | A | Motor Current B | Motor current, circuit B |
| 13 | - | A | Motor Current C | Motor current, circuit C |
| 14 | - | mA | Reset/Setpnt4-20mA Sgnl | 4-20 mA signal, setpoint reset |
| 15 | open/close | - | Customer Interlock | Customer interlock |
| 16 | open/close | - | Ice Done Storage Switch | Ice storage end switch |
| 17 | open/close | - | Occupied Override Switch | Occupied override switch |
| 18 | - | mA | Limit 4-20mA Signal | 4-20 mA signal, capacity limit |
| 19 | open/close | - | Electrical Box Interlock | Electrical box interlock |
| 20 | open/close | - | Cooler Heater command | Evaporator heater command |
| 21 | no/yes | - | BACnet Dongle | BACnet dongle |
| 22 | - | V | Leakage detector 1 val | Leakage detection (Refrigerant leak detection option) |
| 23 | - | V | Leakage detector 2 val | Leakage detection (Refrigerant leak detection option) |
| 24 | off/on | - | ElecBoxFan1 input state | Electrical Box Fan status 1 (units with HFO) |
| 25 | off/on | - | ElecBoxFan2 input state | Electrical Box Fan status 2 (units with HFO) |
| 26 | off/on | - | ElecBoxFan3 input state | Electrical Box Fan status 3 (units with HFO) |

* Depends on the selected language (English by default).



OUTPUTS – Output status

| No. | Status | Unit | Displayed text* | Description |
|-----|--------|------|------------------------|-----------------------------------|
| 1 | off/on | - | Compressor A | Compressor A status |
| 2 | off/on | - | Oil Solenoid Output A | Oil solenoid output, circuit A |
| 3 | off/on | - | Slide Valve 1 Output A | Slide valve 1 output, circuit A |
| 4 | off/on | - | Slide Valve 2 Output A | Slide valve 2 output, circuit A |
| 5 | - | V | Capacity Signal Cir A | 0-10 V capacity signal, circuit A |
| 6 | off/on | - | Compressor B | Compressor B status |
| 7 | off/on | - | Oil Solenoid Output B | Oil solenoid output, circuit B |
| 8 | off/on | - | Slide Valve 1 Output B | Slide valve 1 output, circuit B |
| 9 | off/on | - | Slide Valve 2 Output B | Slide valve 2 output, circuit B |
| 10 | - | V | Capacity Signal Cir B | 0-10 V capacity signal, circuit B |
| 11 | off/on | - | Compressor C | Compressor C status |
| 12 | off/on | - | Oil Solenoid Output C | Oil solenoid output, circuit C |
| 13 | off/on | - | Slide Valve 1 Output C | Slide valve 1 output, circuit C |
| 14 | off/on | - | Slide Valve 2 Output C | Slide valve 2 output, circuit C |
| 15 | - | V | Capacity Signal Cir C | 0-10 V capacity signal, circuit C |

6 - TOUCH PILOT INTERFACE DETAILS



OUTPUTS – Output status (continued)

| No. | Status | Unit | Displayed text* | Description |
|-----|------------|------|--------------------------|--|
| 16 | - | V | Chiller Capacity signal | Chiller capacity signal |
| 17 | off/on | - | Alarm Relay Status | Alarm relay status |
| 18 | off/on | - | Running Relay Status | Running relay status |
| 19 | off/on | - | Alert Relay State | Alert relay state |
| 20 | off/on | - | Shutdown Indicator State | Shutdown indicator status |
| 21 | 0 to 100 | % | Cond 3 Way Valve Pos | Condenser 3-way valve position |
| 22 | off/on | - | Cooler Heater Command | Evaporator heater command status |
| 23 | off/on | - | Ready or Running Status | Unit ready/running status |
| 24 | off/on | - | Reclaim Condenser Heater | Reclaim condenser heater status |
| 25 | off/on | - | Ball Valve Close Out A | Ball valve close output, circuit A |
| 26 | off/on | - | Ball Valve Open OutA | Ball valve open output, circuit A |
| 27 | off/on | - | Ball Valve Close Out B | Ball valve close output, circuit B |
| 28 | off/on | - | Ball Valve Open OutB | Ball valve open output, circuit B |
| 29 | off/on | - | Ball Valve Close Out C | Ball valve close output, circuit C |
| 30 | off/on | - | Ball Valve Open Out C | Ball valve open output, circuit C |
| 31 | - | - | Fan Staging Number A | Fan stage, circuit A |
| 32 | - | - | Fan Staging Number B | Fan stage, circuit B |
| 33 | - | - | Fan Staging Number C | Fan stage, circuit C |
| 34 | 0 to 100 | % | Head Press Act Pos A | Head pressure control – actuator position, circuit A |
| 35 | 0 to 100 | % | Head Press Act Pos B | Head pressure control – actuator position, circuit B |
| 36 | 0 to 100 | % | Head Press Act Pos C | Head pressure control – actuator position, circuit C |
| 37 | off/on | - | Oil Heater Output A | Oil heater output, circuit A |
| 38 | off/on | - | Oil Heater Output B | Oil heater output, circuit B |
| 39 | off/on | - | Oil Heater Output C | Oil heater output, circuit C |
| 40 | off/on | - | 4 Way Refrig Valve A | 4-way refrigerant valve position, circuit A |
| 41 | off/on | - | 4 Way Refrig Valve B | 4-way refrigerant valve position, circuit B |
| 42 | close/open | - | Ball Valve Position A | Ball valve position, circuit A |
| 43 | close/open | - | Ball Valve Position B | Ball valve position, circuit B |
| 44 | close/open | - | Ball Valve Position C | Ball valve position, circuit C |
| 45 | off/on | - | Alarm Relay Status | Alarm relay output status |
| 46 | off/on | - | Electrical Box Fan sw | Electrical box fan status (units with HFO) |
| 47 | 0 to 10 | - | Dry Cool Vfan1 Output | Dry cooler – variable speed fan 1 |
| 48 | 0 to 10 | - | Dry Cool Vfan2 Output | Dry cooler – variable speed fan 2 |
| 49 | off/on | - | Dry Cool fan stage 1 | Dry cooler fan stage 1 |
| 50 | off/on | - | Dry Cool fan stage 2 | Dry cooler fan stage 2 |
| 51 | off/on | - | Dry Cool fan stage 3 | Dry cooler fan stage 3 |
| 52 | off/on | - | Dry Cool fan stage 4 | Dry cooler fan stage 4 |
| 53 | off/on | - | Dry Cool fan stage 5 | Dry cooler fan stage 5 |
| 54 | off/on | - | Dry Cool fan stage 6 | Dry cooler fan stage 6 |
| 55 | off/on | - | Dry Cool fan stage 7 | Dry cooler fan stage 7 |
| 56 | off/on | - | Dry Cool fan stage 8 | Dry cooler fan stage 8 |

* Depends on the selected language (English by default).



PUMPSTAT – Pump status

| No. | Status | Unit | Displayed text* | Description |
|-----|------------|------|--------------------------|---|
| 1 | no/yes | - | Cooler Flow Setpoint Out | Evaporator flow setpoint output |
| 2 | 0 to 1 | - | Cooler Pump #1 Command | Evaporator pump 1 control |
| 3 | 0 to 1 | - | Cooler Pump #2 Command | Evaporator pump 2 control |
| 4 | 0 to 1 | - | Rotate Cooler Pumps ? | Evaporator pumps rotation |
| 5 | open/close | - | Cooler Flow Switch | Evaporator flow switch |
| 6 | 0 to 1 | - | Condenser Pump Command1 | Condenser pump 1 control |
| 7 | 0 to 1 | - | Condenser Pump Command2 | Condenser pump 2 control (not available!) |
| 8 | 0 to 1 | - | Rotate Condenser Pumps ? | Condenser pumps rotation (not available!) |
| 9 | - | kPa | Water pres before cooler | Evaporator entering water pressure |
| 10 | - | kPa | Water pres after cooler | Evaporator leaving water pressure |
| 11 | - | kPa | Water pres before filter | Filter entering water pressure |
| 12 | - | kPa | Water pres after filter | Filter leaving water pressure |
| 13 | - | l/s | Water flow | Water flow rate |
| 14 | - | kW | Cooling power | Cooling power |
| 15 | open/close | - | Condenser Flow Status | Condenser flow status |
| 16 | 0 to 100 | % | Variable speed pump cmd | Variable speed pump command |

* Depends on the selected language (English by default).

6 - TOUCH PILOT INTERFACE DETAILS



RUNTIME – Run times

| No. | Status | Unit | Displayed text* | Description |
|-----|--------|------|-------------------------|--|
| 1 | - | hour | Machine Operating Hours | Unit operating hours |
| 2 | - | - | Machine Starts Number | Number of unit starts |
| 3 | - | hour | Compressor A Hours | Operating hours, compressor A |
| 4 | - | - | Compressor A Starts | Number of starts, compressor A |
| 5 | - | hour | Compressor B Hours | Operating hours, compressor B |
| 6 | - | - | Compressor B Starts | Number of starts, compressor B |
| 7 | - | hour | Compressor C Hours | Operating hours, compressor C |
| 8 | - | - | Compressor C Starts | Number of starts, compressor C |
| 9 | - | hour | Cooler Pump #1 Hours | Operating hours, evaporator pump 1 |
| 10 | - | hour | Cooler Pump #2 Hours | Operating hours, evaporator pump 2 |
| 11 | - | hour | Condenser Pump #1 Hours | Operating hours, condenser pump 1 |
| 12 | - | hour | Condenser Pump #2 Hours | Operating hours, condenser pump 2 (not available!) |
| 13 | - | hour | Free Cool A Pump Hours | Pump operating hours in Free Cooling, circuit A |
| 14 | - | hour | Free Cool B Pump Hours | Pump operating hours in Free Cooling, circuit B |

* Depends on the selected language (English by default).

NOTE: The displayed run times are updated every hour.



MODES – Modes

| No. | Status | Unit | Displayed text* | Description |
|-----|--------|------|--------------------------|--|
| 1 | no/yes | - | Start Up Delay In Effect | Start-up delay in effect |
| 2 | no/yes | - | Second Setpoint In Use | Second setpoint in use |
| 3 | no/yes | - | Reset In Effect | Setpoint reset active |
| 4 | no/yes | - | Demand limit Active | Demand limit active |
| 5 | no/yes | - | Ramp Loading Active | Ramp loading active |
| 6 | no/yes | - | Cooler Heater Active | Evaporator heater active |
| 7 | no/yes | - | Cooler Pump Rotation | Evaporator pump rotation |
| 8 | no/yes | - | Pump Periodic Start | Pump periodic start active |
| 9 | no/yes | - | Night Low Noise Active | Night low noise active |
| 10 | no/yes | - | Master Slave Active | Master/slave mode active |
| 11 | no/yes | - | Auto Changeover Active | Automatic changeover active |
| 12 | no/yes | - | Heating Low EWT Lockout | Heating low EWT lockout |
| 13 | no/yes | - | Condenser Pump Rotation | Condenser pump rotation (not available!) |
| 14 | no/yes | - | Cond Pump Periodic Start | Condenser pump periodic start |
| 15 | no/yes | - | Ice Mode In Effect | Ice storage mode active |
| 16 | no/yes | - | Defrost Active On Cir A | Defrost mode active, circuit A |
| 17 | no/yes | - | Defrost Active On Cir B | Defrost mode active, circuit B |
| 18 | no/yes | - | Free Cooling Active | Free cooling mode active |
| 19 | no/yes | - | Reclaim Active | Reclaim mode active |
| 20 | no/yes | - | Low Suction Circuit A | Low suction, circuit A |
| 21 | no/yes | - | Low Suction Circuit B | Low suction, circuit B |
| 22 | no/yes | - | Low Suction Circuit C | Low suction, circuit C |
| 23 | no/yes | - | Map compressor Circuit A | Compressor mapping, circuit A |
| 24 | no/yes | - | Map compressor Circuit B | Compressor mapping, circuit B |
| 25 | no/yes | - | Map compressor Circuit C | Compressor mapping, circuit C |
| 26 | no/yes | - | High Pres Override Cir A | High pressure override, circuit A |
| 27 | no/yes | - | High Pres Override Cir B | High pressure override, circuit B |
| 28 | no/yes | - | High Pres Override Cir C | High pressure override, circuit C |

* Depends on the selected language (English by default).

6 - TOUCH PILOT INTERFACE DETAILS

21,6°C
.....
67,2%

RECLAIM – Reclaim

| No. | Status | Unit | Displayed text* | Description |
|-----|----------|------|--------------------------|--|
| 1 | 0 to 1 | - | Heat Reclaim Select | Heat reclaim selection |
| 2 | - | °C | Reclaim Entering Fluid | Reclaim entering water temperature |
| 3 | - | °C | Reclaim Leaving Fluid | Reclaim leaving water temperature |
| 4 | 0 to 100 | % | Reclaim Valve Position | Reclaim valve position |
| 5 | - | - | Reclaim Status Circuit A | Reclaim status, circuit A |
| 6 | - | kPa | Pumpdown Pressure Cir A | Pump-down pressure, circuit A |
| 7 | - | °C | Sub Condenser Temp Cir A | Subcooling condenser temperature, circuit A |
| 8 | - | °C | Pumpdown Saturated Tmp A | Pump-down saturated temperature, circuit A |
| 9 | - | ^C | Subcooling Temperature A | Subcooling temperature, circuit A |
| 10 | off/on | - | Air Cond Entering Valv A | Air condenser entering valve status, circuit A |
| 11 | off/on | - | Water Cond Enter Valve A | Water condenser entering valve status, circuit A |
| 12 | off/on | - | Air Cond Leaving Valve A | Air condenser leaving valve status, circuit A |
| 13 | off/on | - | Water Cond Leaving Val A | Water condenser leaving valve status, circuit A |
| 14 | - | - | Reclaim Status Circuit B | Reclaim status, circuit B |
| 15 | - | kPa | Pumpdown Pressure Cir B | Pump-down pressure, circuit B |
| 16 | - | °C | Sub Condenser Temp Cir B | Subcooling condenser temperature, circuit B |
| 17 | - | °C | Pumpdown Saturated Tmp B | Pump-down saturated temperature, circuit B |
| 18 | - | ^C | Subcooling Temperature B | Subcooling temperature, circuit B |
| 19 | off/on | - | Air Cond Entering Valv B | Air condenser entering valve status, circuit B |
| 20 | off/on | - | Water Cond Enter Valve B | Water condenser entering valve status, circuit B |
| 21 | off/on | - | Air Cond Leaving Valve B | Air condenser leaving valve status, circuit B |
| 22 | off/on | - | Water Cond Leaving Val B | Water condenser leaving valve status, circuit B |

* Depends on the selected language (English by default).



DCFC_STA – DC Free Cooling Status Menu

| No. | Status | Unit | Displayed text* | Description |
|-----|-------------|------|--------------------------|--|
| 1 | - | °C | OAT Free Cooling | Free Cooling / Dry Cooler: OAT |
| 2 | - | °C | FC Leaving Water Temp | Free Cooling / Dry Cooler: Leaving water temperature |
| 3 | - | °C | FC Water Loop Temp | Free Cooling / Dry Cooler: Water loop temperature |
| 4 | no/yes | - | Free Cooling Mode Active | Dry Cooler Free Cooling mode active |
| 5 | 0 to 100 | % | FC Capacity | Free Cooling / Dry Cooler capacity |
| 6 | 0 to 20 | - | Fix Speed Fans Stage | Free Cooling / Dry Cooler fan stage (fixed speed fans) |
| 7 | 0 to 100 | % | Varifan Speed | Free Cooling / Dry Cooler: Fan speed |
| 8 | 0 to 100 | % | PID Output Value | Status of PID output |
| 9 | 0 to 999999 | hour | DCFC Operating Hours | Free Cooling / Dry Cooler: Operating hours |
| 10 | 0 to 999999 | - | DCFC Fan Stage 1 Start | DCFC / Fan stage 1: Number of starts |
| 11 | 0 to 999999 | hour | DCFC Fan Stage 1 Hours | DCFC / Fan stage 1: Operating hours |
| 12 | 0 to 999999 | - | DCFC Fan Stage 2 Start | DCFC / Fan stage 2: Number of starts |
| 13 | 0 to 999999 | hour | DCFC Fan Stage 2 Hours | DCFC / Fan stage 2: Operating hours |
| 14 | 0 to 999999 | - | DCFC Fan Stage 3 Start | DCFC / Fan stage 3: Number of starts |
| 15 | 0 to 999999 | hour | DCFC Fan Stage 3 Hours | DCFC / Fan stage 3: Operating hours |
| 16 | 0 to 999999 | - | DCFC Fan Stage 4 Start | DCFC / Fan stage 4: Number of starts |
| 17 | 0 to 999999 | hour | DCFC Fan Stage 4 Hours | DCFC / Fan stage 4: Operating hours |
| 18 | 0 to 999999 | - | DCFC Fan Stage 5 Start | DCFC / Fan stage 5: Number of starts |
| 19 | 0 to 999999 | hour | DCFC Fan Stage 5 Hours | DCFC / Fan stage 5: Operating hours |
| 20 | 0 to 999999 | - | DCFC Fan Stage 6 Start | DCFC / Fan stage 6: Number of starts |
| 21 | 0 to 999999 | hour | DCFC Fan Stage 6 Hours | DCFC / Fan stage 6: Operating hours |
| 22 | 0 to 999999 | - | DCFC Fan Stage 7 Start | DCFC / Fan stage 7: Number of starts |
| 23 | 0 to 999999 | hour | DCFC Fan Stage 7 Hours | DCFC / Fan stage 7: Operating hours |
| 24 | 0 to 999999 | - | DCFC Variable Fan Start | DCFC / Variable speed fan: Number of starts |
| 25 | 0 to 999999 | hour | DCFC Variable Fan Hours | DCFC / Variable speed fan: Operating hours |

* Depends on the selected language (English by default).

6 - TOUCH PILOT INTERFACE DETAILS

21,6°C
.....
67,2%

FREECOOL – Free cooling

| No. | Status | Unit | Displayed text* | Description |
|-----|----------|------|--------------------------|---|
| 1 | - | - | GENERAL PARAMETERS | GENERAL PARAMETERS |
| 2 | 0 to 1 | - | Free Cooling Disable? | Free cooling mode status |
| 3 | - | ^C | LWT-OAT Delta | LWT – OAT Delta |
| 4 | - | - | CIRCUIT A | Circuit A |
| 5 | - | kW | Mechanical Cooling Power | Mechanical cooling power |
| 6 | - | kW | Free Cooling Maxi Power | Free cooling maximum power |
| 7 | - | min | Next session allowed in | Next session allowed after the specified time |
| 8 | - | min | Cooling/FreeCool Timeout | Cooling/free cooling timeout |
| 9 | no/yes | - | Free Cool Conditions OK? | Optimal free cooling conditions |
| 10 | no/yes | - | Free Cool Request ? | Free cooling request |
| 11 | off/on | - | Free Cooling Heaters ? | Free cooling heaters status |
| 12 | no/yes | - | Free Cooling Active | Free cooling status |
| 13 | - | - | Fan Staging Number | Fan stage |
| 14 | off/on | - | Discharge valve Open out | Discharge valve open output |
| 15 | off/on | - | Dischrge valve Close out | Discharge valve close output |
| 16 | - | - | Discharge valve status | Discharge valve status |
| 17 | off/on | - | Bypass valve Open out | Bypass valve open output |
| 18 | off/on | - | Bypass valve Close out | Bypass valve close output |
| 19 | - | - | Bypass valve status | Bypass valve status |
| 20 | off/on | - | Refrigerant Pump Out | Refrigerant pump output |
| 21 | - | kPa | Pump Inlet Pressure | Pump inlet pressure |
| 22 | - | kPa | Pump Outlet Pressure | Pump outlet pressure |
| 23 | - | kPa | Pump Differential Press. | Pump differential pressure |
| 24 | 0 to 100 | % | EXV position | EXV position |
| 25 | - | °C | Free cooling Liquid Tmp | Free cooling liquid temperature |
| 26 | - | ^C | Free cooling Subcool Tmp | Free cooling subcooling temperature |
| 27 | - | ^C | Free cooling Subcool Spt | Free cooling subcooling setpoint |
| 28 | - | - | CIRCUIT B | Circuit B |
| 29 | - | kW | Mechanical Cooling Power | Mechanical cooling power |
| 30 | - | kW | Free Cooling Maxi Power | Free cooling maximum power |
| 31 | - | min | Next session allowed in | Next session allowed after the specified time |
| 32 | - | min | Cooling/FreeCool Timeout | Cooling/free cooling timeout |
| 33 | no/yes | - | Free Cool Conditions OK? | Optimal free cooling conditions |
| 34 | no/yes | - | Free Cool Request ? | Free cooling request |
| 35 | off/on | - | Free Cooling Heaters ? | Free cooling heaters status |
| 36 | no/yes | - | Free Cooling Active | Free cooling status |
| 37 | - | - | Fan Staging Number | Fan stage |
| 38 | off/on | - | Discharge valve Open out | Discharge valve open output |
| 39 | off/on | - | Dischrge valve Close out | Discharge valve close output |
| 40 | - | - | Discharge valve status | Discharge valve status |
| 41 | off/on | - | Bypass valve Open out | Bypass valve open output |
| 42 | off/on | - | Bypass valve Close out | Bypass valve close output |
| 43 | - | - | Bypass valve status | Bypass valve status |
| 44 | off/on | - | Refrigerant Pump Out | Refrigerant pump output |
| 45 | - | kPa | Pump Inlet Pressure | Pump inlet pressure |
| 46 | - | kPa | Pump Outlet Pressure | Pump outlet pressure |
| 47 | - | kPa | Pump Differential Press. | Pump differential pressure |
| 48 | 0 to 100 | % | EXV position | EXV position |
| 49 | - | °C | Free cooling Liquid Tmp | Free cooling liquid temperature |
| 50 | - | ^C | Free cooling Subcool Tmp | Free cooling subcooling temperature |
| 51 | - | ^C | Free cooling Subcool Spt | Free cooling subcooling setpoint |

* Depends on the selected language (English by default).

6 - TOUCH PILOT INTERFACE DETAILS



SETPOINT – Setpoint table





| No. | Status | Default | Unit | Displayed text* | Description |
|-----|--------------|---------|------|--------------------------|--|
| 1 | -28.9 to 26 | 6.7 | °C | Cooling Setpoint 1 | Cooling setpoint 1 |
| 2 | -28.9 to 26 | 6.7 | °C | Cooling Setpoint 2 | Cooling setpoint 2 |
| 3 | -28.9 to 26 | 6.7 | °C | Cooling Ice Setpoint | Ice storage setpoint |
| 4 | 0.1 to 11.1 | 0.6 | ^C | Cooling Ramp Loading | Cooling ramp loading setpoint |
| 5 | 26.7 to 63** | 37.8 | °C | Heating Setpoint 1** | Heating setpoint 1 |
| 6 | 26.7 to 63** | 37.8 | °C | Heating Setpoint 2** | Heating setpoint 2 |
| 7 | 0.1 to 11.1 | 0.6 | ^C | Heating Ramp Loading | Heating ramp loading setpoint |
| 8 | 3.9 to 50 | 23.9 | °C | Cool Changeover Setpt | Cooling changeover setpoint |
| 9 | 0 to 46.1 | 17.8 | °C | Heat Changeover Setpt | Heating changeover setpoint |
| 10 | 26.7 to 60 | 35 | °C | Water Val Condensing Stp | Water valve condensing setpoint |
| 11 | 0 to 100 | 100 | % | Switch Limit Setpoint 1 | Limit setpoint switch 1 |
| 12 | 0 to 100 | 100 | % | Switch Limit Setpoint 2 | Limit setpoint switch 2 |
| 13 | 0 to 100 | 100 | % | Switch Limit Setpoint 3 | Limit setpoint switch 3 |
| 14 | 35 to 50 | 50 | °C | Reclaim Setpoint | Heat reclaim setpoint |
| 15 | 2.8 to 15 | 5 | ^C | Reclaim Deadband | Heat reclaim deadband |
| 16 | 1 to 20 | 5 | ^C | Varipump Delta Temp Stp | Variable speed pump delta temperature setpoint |

* Depends on the selected language (English by default).

** 26.7 to 70.0°C range for units with HFO.

NOTE: Since specific units may not include certain options, some tables provided in the document contain parameters that cannot be configured for a given unit.










6.3 - Alarms menu

| Icon | Displayed text* | Description |
|---|---------------------|---------------------|
|  | Reset Alarms | Alarm reset |
|  | Current Alarms | Current alarms |
|  | Alarm History | Alarm History |
|  | Major Alarm History | Major alarm history |

* Depends on the selected language (English by default).

6 - TOUCH PILOT INTERFACE DETAILS

6.4 - Configuration menu

| Icon | Displayed text* | Description | Associated table |
|---|-------------------------|-------------------------|------------------|
|  | General Configuration | General configuration | GEN_CONF |
|  | Pump Configuration | Pump configuration | PUMPCONF |
|  | User Configuration | User configuration | USERCONF |
|  | Reset Configuration | Reset configuration | RESETCFG |
|  | Schedule Menu | Schedule menu | SCHEDULE |
|  | Holiday Menu | Holiday menu | HOLIDAY |
|  | Broadcast Menu | Broadcast menu | BROCASTS |
|  | Date/Time Configuration | Date/time configuration | DATETIME |
|  | Control Identification | Control identification | CTRL_ID |

* Depends on the selected language (English by default).



GEN_CONF – General configuration

| No. | Status | Default | Unit | Displayed text* | Description |
|-----|------------|---------|------|--------------------------|---|
| 1 | 0 to 2 | 0 | - | Cir Priority Sequence | Circuit priority |
| 2 | | | | 0=Auto, 1=A Prio | 0 = Automatic circuit selection 1 = Circuit A priority |
| 3 | | | | 2=B Prio | 2 = Circuit B priority |
| 4 | no/yes | no | - | Staged Loading Sequence | Staged loading sequence |
| 5 | no/yes | no | - | Ramp Loading Select | Ramp loading selection |
| 6 | 1 to 15 | 1 | min | Unit Off to On Delay | Unit Off to On delay |
| 7 | 00:00 | 0 | - | Night Mode Start Hour | Night mode start time |
| 8 | 00:00 | 0 | - | Night Mode End Hour | Night mode end time |
| 9 | 0 to 100 | 100 | % | Night Capacity Limit | Night capacity limit |
| 10 | | | | Basic Menu Configuration | Basic menu configuration |
| 11 | | | | 0 = All Access | 0 = All access |
| 12 | | | | 1 = no alarm menu | 1 = No alarm menu |
| 13 | | | | 2 = no setpoint menu | 2 = No setpoint menu |
| 14 | | | | 3 = 1 + 2 | 3 = No alarm and no setpoint menu |
| 15 | 0 to 2 | 0 | - | Demand Limit Type Select | Demand limit selection |
| 16 | | | | 0 = None | 0 = None |
| 17 | | | | 1 = Switch Control | 1 = Switch control |
| 18 | | | | 2 = 4-20mA Control | 2 = 4-20 mA control |
| 19 | 0 to 20 | 0 | mA | mA For 100% Demand Limit | 100% demand Limit (mA) |
| 20 | 0 to 20 | 10 | mA | mA For 0% Demand Limit | 0% demand Limit (mA) |
| 21 | no/yes | no | - | Current Limit Select | Current limit selection |
| 22 | 0 to 4000 | 2000 | A | CurrentLimit at 100% | Current limit at 100% |
| 23 | 14.4 to 15 | 10 | ^C | Free Cooling Delta T Th | Free cooling delta temperature |
| 24 | 20 to 300 | 30 | min | Full Load Timeout | Full load timeout |
| 25 | no/yes | no | - | Ice Mode Enable | Ice mode enabled |
| 26 | no/yes | no | - | Reverse Alarms Relay | Reverse alarms relay |

* Depends on the selected language (English by default).

6 - TOUCH PILOT INTERFACE DETAILS



PUMPCONF – Pump configuration

| No. | Status | Default | Unit | Displayed text* | Description |
|-----|------------|---------|------|--------------------------|---------------------------------------|
| 1 | 0 to 4 | 0 | - | Condenser Pumps Sequence | Condenser pumps sequence ** |
| 2 | 0 to 4 | 0 | - | Cooler Pumps Sequence | Evaporator pumps sequence |
| 3 | | | | 0 = No Pump | 0 = No pump |
| 4 | | | | 1 = One Pump Only | 1 = One pump |
| 5 | | | | 2 = Two Pumps Auto | 2 = Two pumps automatic control |
| 6 | | | | 3 = Pump#1 Manual | 3 = Pump 1 manual |
| 7 | | | | 4 = Pump#2 Manual | 4 = Pump 2 manual |
| 8 | 24 to 3000 | 48 | hour | Pump Auto Rotation Delay | Pump rotation delay |
| 9 | no/yes | no | - | Pump Sticking Protection | Pump sticking protection |
| 10 | no/yes | no | - | Stop Pump During Standby | Pump stop when the unit is in standby |
| 11 | no/yes | yes | - | Flow Checked If Pump Off | Flow check when the pump is off |
| 12 | no/yes | no | - | Cooler Pump Off In Heat | Evaporator pump off in Heating |
| 13 | no/yes | no | - | Cond Pump Off In Cool | Condenser pump off in Cooling |

* Depends on the selected language (English by default).

** Please note that the unit can control only one condenser pump. This value can be set to "0" or "1".



USERCONF – User configuration

| No. | Status | Default | Unit | Displayed text* | Description |
|-----|-----------|---------|------|-------------------------|--|
| 1 | 1 to 9999 | 11 | - | User Password | User password |
| 2 | 0 to 1 | 0 | - | Language List | Selected language list |
| 3 | | | | 0 = eng/spa/fre/ger/dut | Languages available when "language list" is set to "0" |
| 4 | | | | chi/ita/por/rus/und | |
| 5 | | | | 1 = eng/spa/fre/ger/dut | Languages available when "language list" is set to "1" |
| 6 | | | | tur/ita/por/rus/und | |

* Depends on the selected language (English by default).



RESETCFG – Reset configuration

| No. | Status | Default | Unit | Displayed text* | Description |
|-----|---------------|---------|------|--------------------------|--------------------------------------|
| 1 | 0 to 4 | 0 | - | Cooling Reset Select | Cooling reset selection |
| 2 | 0 to 4 | 0 | - | Heating Reset Select | Heating reset selection |
| 3 | | | | 0=None, 1=OAT | 0 = None 1 = OAT |
| 4 | | | | 2=Delta T, 4=Space Temp | 2 = Delta T 4 = Space temperature |
| 5 | | | | 3=4-20mA control | 3 = 4-20 mA control |
| 6 | | | | Cooling | Cooling |
| 7 | -10 to 51.7 | -10 | °C | OAT No Reset Value | OAT, no reset value |
| 8 | -10 to 51.7 | -10 | °C | OAT Full Reset Value | OAT, max. reset value |
| 9 | 0 to 13.9 | 0 | ^C | Delta T No Reset Value | Delta T, no reset value |
| 10 | 0 to 13.9 | 0 | ^C | Delta T Full Reset Value | Delta T, max. reset value |
| 11 | 0 to 20 | 0 | mA | Current No Reset Value | Current, no reset value |
| 12 | 0 to 20 | 0 | mA | Current Full Reset Value | Current, max. reset value |
| 13 | -10 to 51.7 | -10 | °C | Space T No Reset Value | Space temperature, no reset value |
| 14 | -10 to 51.7 | -10 | °C | Space T Full Reset Value | Space temperature, max. reset value |
| 15 | -16.7 to 16.7 | 0 | ^C | Cooling Reset Deg. Value | Maximum cooling reset value |
| 16 | | | | Heating | Heating |
| 17 | -10 to 51.7 | -10 | °C | OAT No Reset Value | OAT, no reset value |
| 18 | -10 to 51.7 | -10 | °C | OAT Full Reset Value | OAT, max. reset value |
| 19 | 0 to 13.9 | 0 | ^C | Delta T No Reset Value | Delta T, no reset value |
| 20 | 0 to 13.9 | 0 | ^C | Delta T Full Reset Value | Delta T, max. reset value |
| 21 | 0 to 20 | 0 | mA | Current No Reset Value | Current, no reset value |
| 22 | 0 to 20 | 0 | mA | Current Full Reset Value | Current, max. reset value |
| 23 | -10 to 51.7 | -10 | °C | Space T No Reset Value | Space temperature, no reset value |
| 24 | -10 to 51.7 | -10 | °C | Space T Full Reset Value | Space temperature, max. reset value |
| 25 | -16.7 to 16.7 | 0 | ^C | Heating Reset Deg. Value | Maximum heating reset value |
| 26 | -4 to 32 | -17.8 | °C | Heating OAT threshold | Heating OAT threshold |
| 27 | no/yes | no | - | HSM Both Command Select | HSM both command selection |
| 28 | no/yes | no | - | Auto Changeover Select | Automatic changeover selection |

* Depends on the selected language (English by default).

6 - TOUCH PILOT INTERFACE DETAILS



SCHEDULE – Schedule configuration

| No. | Name | Displayed text* | Description |
|-----|----------|--------------------------|---------------------------------------|
| 1 | OCCPC01S | OCCPC01S - Schedule Menu | Unit on/off time schedule |
| 2 | OCCPC02S | OCCPC02S - Schedule Menu | Unit setpoint selection time schedule |

* Depends on the selected language (English by default).



HOLIDAY – Holiday configuration

| No. | Status | Default | Displayed text* | Description |
|-----|--------|---------|---------------------|-------------------------|
| 1 | 0-12 | 0 | Holiday Start Month | Holiday start month |
| 2 | 0-31 | 0 | Start Day | Holiday start day |
| 3 | 0-99 | 0 | Duration (days) | Holiday duration (days) |

* Depends on the selected language (English by default).



BROCASTS – Broadcast configuration

| No. | Status | Default | Displayed text* | Description |
|---|----------------|---------|-------------------------|--|
| 1 | 0 to 2 | 2 | Activate | Not applicable |
| OAT Broadcast | | | | |
| 2 | 0 to 239 | 0 | Bus | Bus number of the unit with outdoor temperature sensor |
| 3 | 0 to 239 | 0 | Element | Element number of the unit with outdoor temperature sensor |
| 4 | disable/enable | disable | Daylight Savings Select | Summer/winter time activation (daylight saving selection) |
| Daylight Savings Select – Summer time (entering) | | | | |
| 5 | 1 to 12 | 3 | Month | Month |
| 6 | 1 to 7 | 7 | Day of Week (1=Monday) | Day of the week (1 = Monday) |
| 7 | 1 to 5 | 5 | Week Number of Month | Week of the month |
| Daylight Savings Select – Winter time (leaving) | | | | |
| 8 | 1 to 12 | 10 | Month | Month |
| 9 | 1 to 7 | 7 | Day of Week (1=Monday) | Day of the week (1 = Monday) |
| 10 | 1 to 5 | 5 | Week Number of Month | Week of the month |

* Depends on the selected language (English by default).



DATETIME – Date/Time configuration

| No. | Status | Default | Displayed text* | Description |
|-----------------------------|---------------|---------|------------------------|--------------------------------|
| Date (DD/MM/YY) | | | | |
| 1 | 1 to 31 | - | Day of month | Day of the month |
| 2 | 1 to 12 | - | Month of year | Month |
| 3 | 0 to 99 | - | Year | Year |
| 4 | Monday-Sunday | - | Day of Week | Day of the week |
| Time (HH:MM) | | | | |
| 5 | 0 to 24 | hour | Hour | Hour |
| 6 | 0 to 59 | min | Minute | Minutes |
| Daylight Saving Time | | | | |
| 7 | no/yes | - | Daylight sav. time on | Daylight saving time active |
| 8 | no/yes | - | Daylight sav. time off | Daylight saving time inactive |
| 9 | no/yes | - | Tomorrow is a holiday | The following day is a holiday |
| 10 | no/yes | - | Today is a holiday | The present day is a holiday |

* Depends on the selected language (English by default).

6 - TOUCH PILOT INTERFACE DETAILS



CTRL_ID – Control ID configuration

| No. | Status | Default | Displayed text* | Description |
|-----|------------------|--------------------|----------------------|---|
| 1 | 0 to 239 | 0 | CCN Element Number | Element number |
| 2 | 0 to 239 | 1 | CCN Bus Number | Bus number |
| 3 | 9600/19200/38400 | 9600 | CCN Baud Rate | Communication speed |
| 4 | - | 30XAXW Touch Pilot | Device Description | Unit description |
| 5 | - | | Location Description | Location description: The number corresponds to the country |
| 6 | - | ECG-SR-20M47010 | Software Part Number | Software version |
| 7 | - | | Serial Number | Serial number (MAC address) |

* Depends on the selected language (English by default).

7 - TOUCH PILOT CONTROL OPERATION

This section points out the most significant control functionalities, e.g. unit start/stop operation, heat/cool control. It also gives instructions on how to perform critical operations of the main control system.

7.1 - Start/Stop control

The unit state is determined based on a number of factors, including its operating type, active overrides, open contacts, master/slave configuration, or alarms triggered due to operating conditions.

The table given below summarises the unit control type and its running status with regard to the following parameters:

- **Operating type:** Operating type is selected using the Start/Stop button on the user interface.

| | |
|------|----------------|
| LOFF | Local off |
| L-C | Local on |
| L-SC | Local schedule |
| rEM | Remote |
| Net. | Network |
| MASt | Master unit |

- **Start/stop force command:** Chiller start/stop force command can be used to control the chiller state in the Network operating type.

- Command set to stop: The unit is halted.
- Command set to start: The unit runs in accordance with schedule 1.

- **Remote start/stop contact status:** Start/stop contact can be used to control the chiller state in the Remote operating type.

- **Master control type:** When the unit is the master unit in a two-chiller lead/lag arrangement, the master unit may be set to be controlled locally, remotely or via network (see also 7.15).

- **Start/stop time schedule:** Occupied or unoccupied status of the unit.

- **Network emergency stop command:** If activated, the unit shuts down regardless of the active operating type.

- **General alarm:** The unit shuts down due to failure.

7.2 - Unit stop function

This function controls the unit compressor capacity reduction. If there is an alarm or a demand to stop, it forces the compressors to the minimum capacity before stopping them.

7.3 - Heating/Cooling selection

For units configured in the heat pump mode, heating/cooling selection can be controlled in various ways, depending on the active operating type. By default, the cooling mode is selected. Heating/cooling control can be automatic or manual.

Heating/Cooling selection can be determined as follows:

- locally at the unit in the GENUNIT menu,
- remotely via the heating/cooling selection contact if the unit is in the Remote operating type,
- via a network command if the unit is in the Network operating type.

In the automatic mode, the outdoor air temperature determines the heating/cooling/standby changeover (see the SETPOINT menu for cooling and heating mode changeover thresholds). The automatic changeover is optional and requires user configuration (GENUNIT – General Parameters).

| Parameter status | | | | | |
|------------------|--------------|---|---------------------------------------|------------------|----------------|
| On/off status | Control type | Heating/Cooling selection in local mode | Heating/Cooling contact in local mode | Heat/Cool select | Operating mode |
| off | - | - | - | - | cooling |
| on | local | cooling | - | - | cooling |
| on | local | heating | - | - | heating |
| on | remote | - | on cooling | - | cooling |
| on | remote | - | on heating | - | heating |
| on | network | - | - | cooling | cooling |
| on | network | - | - | heating | heating |

NOTE: Please remember that the automatic changeover mode cannot be selected on water-cooled units.

| Active operating type | | | | | | Parameters status | | | | | | Control type | Unit state |
|-----------------------|--------|--------|--------|--------|--------|--------------------------|---------------------------|---------------------|--------------------------|----------------------------|---------------|--------------|------------|
| LOFF | L-C | L-SC | rEM | Net. | MASt | Start/stop force command | Remote start/stop contact | Master control type | Start/stop time schedule | Network emergency shutdown | General alarm | | |
| - | - | - | - | - | - | - | - | - | - | enabled | - | - | off |
| - | - | - | - | - | - | - | - | - | - | - | yes | - | off |
| active | - | - | - | - | - | - | - | - | - | - | - | local | off |
| - | - | active | - | - | - | - | - | - | unoccupied | - | - | local | off |
| - | - | - | active | - | - | - | open | - | - | - | - | remote | off |
| - | - | - | active | - | - | - | - | - | unoccupied | - | - | remote | off |
| - | - | - | - | active | - | disabled | - | - | - | - | - | network | off |
| - | - | - | - | active | - | - | - | - | unoccupied | - | - | network | off |
| - | - | - | - | - | active | - | - | local | unoccupied | - | - | local | off |
| - | - | - | - | - | active | - | open | remote | - | - | - | remote | off |
| - | - | - | - | - | active | - | - | remote | unoccupied | - | - | remote | off |
| - | - | - | - | - | active | disabled | - | network | - | - | - | network | off |
| - | - | - | - | - | active | - | - | network | unoccupied | - | - | network | off |
| - | active | - | - | - | - | - | - | - | - | disabled | no | local | on |
| - | - | active | - | - | - | - | - | - | occupied | disabled | no | local | on |
| - | - | - | active | - | - | - | closed | - | occupied | disabled | no | remote | on |
| - | - | - | - | active | - | enabled | - | - | occupied | disabled | no | network | on |
| - | - | - | - | - | active | - | - | local | occupied | disabled | no | local | on |
| - | - | - | - | - | active | - | closed | remote | occupied | disabled | no | remote | on |
| - | - | - | - | - | active | enabled | - | network | occupied | disabled | no | network | on |

7 - TOUCH PILOT CONTROL OPERATION

7.4 - Pumps control

The main control can manage one or two water exchanger pumps, determining each pump on/off state. Both pumps cannot run together. The pump is turned on when this option is configured and when the unit is running.

The pump is turned off when the unit is shut down due to an alarm unless the fault is a frost protection error. The pump can be started in particular operating conditions when the water exchanger heater is active.

If the pump has failed and another pump is available, the unit is stopped and started again with the second pump. If there is no pump available, the unit shuts down.

Units are fitted with the flow switch, allowing for the water flow control. For more information about actuators, see *Water flow switch* in section 3.8.

7.4.1 - Pumps configuration

Basic pump configuration can be performed via the Configuration menu (PUMPCONF – Pump Configuration). Only logged-in users can access the menu (see also section 4.6). The unit must be stopped.

For units with two pumps, these pumps can be controlled automatically or each pump can be started manually.

| Pump(s) available | Pumps sequence (PUMPCONF) |
|-----------------------|--|
| No pump | 0 (no pump) |
| One fixed-speed pump | 1 (one pump only) |
| Two fixed-speed pumps | 2 (two pumps auto) 3 (pump#1 manual) 4 (pump#2 manual) |

7.4.2 - Automatic pump selection

If two pumps are controlled and the reversing function has been selected (PUMPCONF – Pump Configuration), the control tries to limit the pump run time to the configured pump changeover delay. If this delay has elapsed, the pump reversing function is activated.

7.4.3 - Customer pump

30XW chillers as well as 30XB chillers with option 17 may be fitted with one external variable speed cooler pump (often also referred to as “customer cooler pump”).

Customer cooler pump can be configured as follows:

| Pump available | Cooler Pumps Sequence (PUMPCONF) |
|------------------------------------|----------------------------------|
| No pump | 0 (no pump) |
| One pump (fixed or variable speed) | 1 (one pump only) |

Depending on the unit (30XW/30XB), the pump is commanded by one of the following outputs:

- 0-10V output on AUX1 board for single-circuit 30XW chillers,
- 0-10V output on the second SIOB board for dual-circuit 30XW chillers and 30XB chillers with option 17.

The “Varipump Delta Temp Stp” parameter in the SETPOINT menu is used to define the delta T that has to be maintained between cooler entering and leaving water temperatures.

7.4.4 - Pumps protection

The control provides the option to automatically start the pump each day at 14:00 for 2 seconds when the unit is off. The heater for the heat exchanger and the water pump (for units with a pump) can be energised so that it protects the heat exchanger or the water pump against any damage when the unit is shut down for a long time at low outdoor temperature.

If the unit is fitted with two pumps, the first pump is started on even days and the second pump is started on odd days. Starting the pump periodically for a few seconds extends the lifetime of the pump bearings and the tightness of the pump seal. Periodical pump quick start can be selected via the Configuration menu (Pump Sticking Protection, PUMPCONF – Pump Configuration).

7.5 - Condenser water pump control

The water condenser pump control applies to air-cooled units fitted with the optional heat reclaim module as well as water-cooled units. This function ensures constant water pumps control, providing the optimum condenser water flow rate and operating cost savings.

7 - TOUCH PILOT CONTROL OPERATION

7.6 - Control point

The control point represents the water temperature that the unit must produce. It enables to decrease the required capacity depending on the unit load operating conditions.

Control point = Active setpoint + Reset

The control point is calculated based on the active setpoint and the reset calculation.

The forced value can be used instead of any other setpoint calculation only when the unit is in the Network operating type.

7.6.1 - Active setpoint

Two setpoints can be selected. Depending on the current operation type, the active setpoint can be selected manually in the Main menu (GENUNIT – General Parameters), with the volt-free user contacts, with network commands (CCN or BACnet) or automatically with the setpoint time schedule (schedule 2).

The following tables summarise possible selections depending on the control type (Local, Remote or Network) and the following parameters:

- **Heating or Cooling operating mode:** Heat/Cool select (GENUNIT menu)
- **Setpoint selected via the Touch Pilot user interface:** Setpoint select permits selection of the active setpoint if the unit is in the Local operating type (GENUNIT menu)
- **Setpoint switch status:** Remote setpoint switch (INPUTS menu)
- **Schedule 2 status:** Schedule for setpoint selection

LOCAL OPERATING TYPE

| Parameter status | | | | | | Active setpoint |
|--------------------------------|--------------------|---|---------------------------|-----------------|-------------------|----------------------|
| Heating/cooling operating mode | Setpoint selection | Heating/Cooling selection in local mode | Ice storage configuration | Setpoint switch | Schedule 2 status | |
| cooling | csp1 | - | * | * | - | cooling setpoint 1 |
| cooling | csp2 | no | * | * | - | cooling setpoint 2 |
| cooling | csp2 | yes | closed | * | | cooling setpoint 2 |
| cooling | csp2 | yes | open | * | | ice storage setpoint |
| cooling | auto | - | * | * | occupied | cooling setpoint 1 |
| cooling | auto | no | * | * | unoccupied | cooling setpoint 2 |
| cooling | auto | yes | closed | * | unoccupied | cooling setpoint 2 |
| cooling | auto | yes | open | * | unoccupied | ice storage setpoint |
| heating | hsp1 | - | * | * | - | heating setpoint 1 |
| heating | hsp2 | - | * | * | - | heating setpoint 2 |
| heating | auto | - | * | * | occupied | heating setpoint 1 |
| heating | auto | - | * | * | unoccupied | heating setpoint 2 |

*Any configuration, (-) default configuration.

REMOTE OPERATING TYPE

| Parameter status | | | | | | Active setpoint |
|--------------------------------|--------------------|---------------------------|------------------|-----------------|-------------------|----------------------|
| Heating/cooling operating mode | Setpoint selection | Ice storage configuration | Ice done contact | Setpoint switch | Schedule 2 status | |
| cooling | - | - | * | open | - | cooling setpoint 1 |
| cooling | - | no | * | closed | - | cooling setpoint 2 |
| cooling | - | yes | closed | closed | - | cooling setpoint 2 |
| cooling | - | yes | open | closed | - | ice storage setpoint |
| heating | - | - | * | open | - | heating setpoint 1 |
| heating | - | - | * | closed | - | heating setpoint 2 |

*Any configuration, (-) default configuration.

NETWORK OPERATING TYPE

| Parameter status | | | | | | Active setpoint |
|--------------------------------|--------------------|---------------------------|------------------|-----------------|-------------------|--------------------|
| Heating/cooling operating mode | Setpoint selection | Ice storage configuration | Ice done contact | Setpoint switch | Schedule 2 status | |
| cooling | - | - | * | * | occupied | cooling setpoint 1 |
| cooling | - | - | * | * | unoccupied | cooling setpoint 2 |
| heating | - | - | * | * | occupied | heating setpoint 1 |
| heating | - | - | * | * | unoccupied | heating setpoint 2 |

*Any configuration, (-) default configuration.

NOTE: Ice storage configuration and ice done contact apply only to units with the optional energy management module.

7 - TOUCH PILOT CONTROL OPERATION

7.6.2 - Reset

Reset means the active setpoint is modified so that less machine capacity is required. In the cooling mode the setpoint is increased, whereas in the heating mode it is decreased. This modification is in general a reaction to a drop in the load.

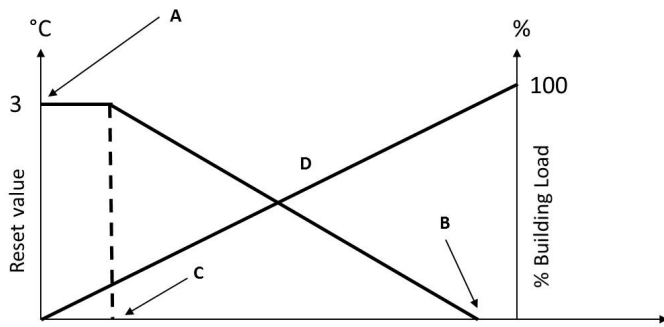
The reset can be based on the following parameters:

- OAT that gives the measure of the load trends for the building
- Return water temperature (ΔT provides the average building load)
- Space temperature (EMM option)
- Dedicated 4-20 mA input

The reset source and the reset parameters can be configured in the Main menu (RESETCFG – Reset Configuration). In response to a drop in the reset source, the cooling setpoint is normally reset upwards to optimise unit performance.

The amount of reset is determined by linear interpolation based on the following parameters:

- A reference at which reset is zero (no reset value)
- A reference at which reset is maximum (full reset value)
- The maximum reset value



| | | |
|-----------------|-----------------------------|-------------------|
| 20 | Reset based on OAT | 25 |
| 0 | Reset based on delta T | 3 |
| 4 | Reset based on analog input | 20 |
| no_reset | selection | full_reset |

Legend

- A: Maximum reset value
- B: Reference for zero reset
- C: Reference for maximum reset
- D: Building load

7.7 - Capacity limitation

The Touch Pilot control system allows for the constant control of the unit capacity by setting its maximum allowable capacity.

The main control system enables to limit the unit capacity using one of the external orders:

- By means of user-controlled volt-free contacts. Units without the energy management module have one contact. Units with the energy management module permit three capacity limitation levels (see also section 3.9.4). The unit capacity can never exceed the limit setpoint activated by these contacts. The limit setpoints can be modified in the SETPOINT menu.
- By lag limit set by the master unit (master/slave assembly).
- By night mode limitation control. The demand limit value in the night mode is selectable if the value is below the selected limit. A limit value of 100% means that the unit can use all capacity stages.

In certain conditions, the unit power consumption can exceed the capacity limitation threshold to protect the compressors.

7.8 - Current limitation

Current limitation is used via the demand limit function. If the current limitation is active (Current Limit Select in the GEN_CONF menu), the control calculates the sum of compressors current to obtain the total compressor current. If this value exceeds the pre-defined limit, the control commands a reduction of the compressor load, until it is below the limit again. Before loading a capacity stage, the control estimates the future total compressor current and ensures that it does not exceed the limit.

The current limit is based on two parameters:

- The current limit that corresponds to 100% capacity (CurrentLimit at 100%, GEN_CONF – General Configuration)
- The active demand limit determined either by the demand limit contact (see also section 3.9.4) or by the network (Active Demand Limit Val, GENUNIT – General Parameters)

Chiller current limit is displayed in the GENUNIT menu.

Current limitation is disabled if the unit operates in the master/slave mode, the unit is controlled by a System Manager or the night mode is active.

7.9 - Capacity control

This function adjusts the capacity using the compressor slide valve to keep the water exchanger temperature at its setpoint. The control system continuously takes account of the temperature error with respect to the setpoint, the rate of change in this error and the difference between entering and leaving water temperatures in order to determine the optimal moment at which to add or withdraw capacity.

Compressors are started and stopped in a sequence designed to equalise the number of start-ups (value weighted by their operating time). For more information about compressors sequence, see *Balanced loading sequence* and *Staged loading sequence* in section 7.13.

7 - TOUCH PILOT CONTROL OPERATION

7.10 - Night mode

Night mode allows users to configure the unit to operate with specific parameters in a specific time period. During the night period, the unit capacity is limited and the number of operating fans is reduced.

The night period is defined by a start time and an end time that are the same for each day of the week. The Night mode settings or the maximum capacity value can be configured via the Configuration menu (GEN_CONF – General Configuration).

Only logged-in users can modify Night Mode settings (see also section 4.6).

7.11 - Head pressure control

For air-cooled units, the condensing pressure of each circuit is generated by 10 fans maximum. As an option, a speed variator can be used to control up to four fans so that the speed of the fans is adjusted to maintain the head pressure setpoint. The condensing pressure is independently controlled in each circuit based on the saturated condensing temperature. The control permanently adjusts its setpoint to guarantee optimal performance and ensure anti-short-cycle protection of the fans.

For water-cooled units, condensing pressure control is assured if the three-way valve option is selected. The saturated condensing temperature is controlled based on a user-configurable fixed setpoint (SETPOINT menu). The three-way valve control can be configured only by Carrier service.

7.12 - Circuit lead/lag selection (multi-circuit units)

This function determines the lead and lag circuit on dual-circuit or triple-circuit units. It controls the start/stop sequence of the refrigeration circuits called circuit A, circuit B or circuit C. The circuit authorised to start first is the lead circuit. Lead circuit is used first for capacity increases and at the same time should be decreased last when decreasing capacity. The lead/lag circuits can be selected manually or automatically according to the unit configuration (GEN_CONF – General Configuration).

■ **Automatic lead/lag circuit determination:** The control system determines the lead circuit to equalise the operating time of each circuit (value weighted by the number of start-ups of each circuit). As a result, the circuit with the lowest number of operating hours always starts first.

■ **Manual lead/lag circuit determination:** Circuit A, B or C selected as the lead circuit. The selected circuit is always the leader. It is the first to start and the last to stop.

7.13 - Compressor loading sequence (multi-circuit units)

This function determines in which order the circuit capacity is changed. Compressor loading is managed by starting/stopping the compressors and controlling the position of the slide valve. Two types of sequencing are available and can be configured by the user via the Touch Pilot user interface (GEN_CONF – General Configuration).

■ **Balanced loading sequence:** The control maintains equal capacity between all circuits as the machine loads and unloads.

■ **Staged loading sequence:** The control loads the lead circuit completely before the lag circuits are started. When the load is decreasing, the lag circuits are unloaded first.

Staged loading sequence is incorporated under the following conditions:

- One of the circuits is shut down due to its failure
- One of the circuits is in capacity override mode
- Remaining circuits are shut down or fully charged

7.14 - Circuit capacity loading sequence

7.14.1 - Dual circuit – balanced capacity loading

| Loading sequence (%) | | Unloading sequence (%) | |
|----------------------|-------------|------------------------|-------------|
| Lead circuit | Lag circuit | Lead circuit | Lag circuit |
| 0 | 0 | 100 | 100 |
| 30 (15) | 0 | 100 | 95 |
| 35 | 0 | 95 | 95 |
| 40 | 0 | 95 | 90 |
| 45 | 0 | 90 | 90 |
| 50 | 0 | 90 | 85 |
| 55 | 0 | 85 | 85 |
| 60 | 0 | 85 | 80 |
| 65 | 0 | 80 | 80 |
| 70 | 0 | 80 | 75 |
| 70 | 30 (15) | 75 | 75 |
| 70 | 35 | 75 | 70 |
| 70 | 40 | 70 | 70 |
| 70 | 45 | 70 | 65 |
| 70 | 50 | 65 | 65 |
| 70 | 55 | 65 | 60 |
| 70 | 65 | 60 | 60 |
| 70 | 70 | 60 | 55 |
| 75 | 70 | 55 | 55 |
| 75 | 75 | 55 | 50 |
| 80 | 75 | 50 | 50 |
| 80 | 80 | 50 | 45 |
| 85 | 80 | 45 | 45 |
| 85 | 85 | 45 | 40 |
| 90 | 85 | 40 | 40 |
| 90 | 90 | 40 | 35 |
| 95 | 90 | 40 | 30 (15) |
| 95 | 95 | 40 | 0 |
| 100 | 95 | 35 | 0 |
| 100 | 100 | 30 (15) | 0 |
| 100 | 100 | 0 | 0 |

7.14.2 - Dual circuit – priority given to one circuit

| Loading sequence (%) | | Unloading sequence (%) | |
|----------------------|-------------|------------------------|-------------|
| Lead circuit | Lag circuit | Lead circuit | Lag circuit |
| 0 | 0 | 100 | 100 |
| 30 (15) | 0 | 100 | 95 |
| 35 | 0 | 100 | 90 |
| 40 | 0 | 100 | 85 |
| 45 | 0 | 100 | 80 |
| 50 | 0 | 100 | 75 |
| 55 | 0 | 100 | 70 |
| 60 | 0 | 100 | 65 |
| 65 | 0 | 100 | 60 |
| 70 | 0 | 100 | 55 |
| 75 | 0 | 100 | 50 |
| 80 | 0 | 100 | 45 |
| 85 | 0 | 100 | 40 |
| 90 | 0 | 100 | 35 |
| 95 | 0 | 100 | 30 (15) |
| 100 | 0 | 95 | 30 (15) |
| 100 | 30 (15) | 90 | 30 (15) |
| 100 | 35 | 85 | 30 (15) |
| 100 | 40 | 80 | 30 (15) |
| 100 | 45 | 75 | 30 (15) |
| 100 | 50 | 70 | 30 (15) |
| 100 | 55 | 70 | 0 |

7 - TOUCH PILOT CONTROL OPERATION

| Loading sequence (%) | | Unloading sequence (%) | |
|----------------------|-------------|------------------------|-------------|
| Lead circuit | Lag circuit | Lead circuit | Lag circuit |
| 100 | 60 | 65 | 0 |
| 100 | 65 | 60 | 0 |
| 100 | 70 | 55 | 0 |
| 100 | 75 | 50 | 0 |
| 100 | 80 | 45 | 0 |
| 100 | 85 | 40 | 0 |
| 100 | 90 | 35 | 0 |
| 100 | 95 | 30 (15) | 0 |
| 100 | 100 | 0 | 0 |

NOTE: (15) minimum capacity for standard water-cooled units (without the option for high condensing temperature).

7.14.3 - Triple circuit – balanced capacity loading

| Loading sequence (%) | | | Unloading sequence (%) | | |
|----------------------|-------------|-------------|------------------------|-------------|-------------|
| Lead circ. | Lag circ. 1 | Lag circ. 2 | Lead circ. | Lag circ. 1 | Lag circ. 2 |
| 0 | 0 | 0 | 100 | 100 | 100 |
| 30 | 0 | 0 | 100 | 100 | 95 |
| 35 | 0 | 0 | 100 | 95 | 95 |
| 40 | 0 | 0 | 95 | 95 | 95 |
| 45 | 0 | 0 | 95 | 95 | 90 |
| 50 | 0 | 0 | 95 | 90 | 90 |
| 55 | 0 | 0 | 90 | 90 | 90 |
| 60 | 0 | 0 | 90 | 90 | 85 |
| 65 | 0 | 0 | 90 | 85 | 85 |
| 70 | 30 | 0 | 85 | 85 | 85 |
| 70 | 35 | 0 | 85 | 85 | 80 |
| 70 | 40 | 0 | 85 | 80 | 80 |
| 70 | 45 | 0 | 80 | 80 | 80 |
| 70 | 50 | 0 | 80 | 80 | 75 |
| 70 | 55 | 0 | 80 | 75 | 75 |
| 70 | 60 | 0 | 75 | 75 | 75 |
| 70 | 65 | 0 | 75 | 75 | 70 |
| 70 | 70 | 0 | 75 | 70 | 70 |
| 70 | 70 | 30 | 70 | 70 | 70 |
| 70 | 70 | 35 | 70 | 70 | 65 |
| 70 | 70 | 40 | 70 | 65 | 65 |
| 70 | 70 | 45 | 65 | 65 | 65 |
| 70 | 70 | 50 | 65 | 65 | 60 |
| 70 | 70 | 55 | 65 | 60 | 60 |
| 70 | 70 | 60 | 60 | 60 | 60 |
| 70 | 70 | 65 | 60 | 60 | 55 |
| 70 | 70 | 70 | 60 | 55 | 55 |
| 75 | 70 | 70 | 55 | 55 | 55 |
| 75 | 75 | 70 | 55 | 55 | 50 |
| 75 | 75 | 75 | 55 | 50 | 50 |
| 80 | 75 | 75 | 50 | 50 | 50 |
| 80 | 80 | 75 | 50 | 50 | 45 |
| 80 | 80 | 80 | 50 | 45 | 45 |
| 85 | 80 | 80 | 45 | 45 | 45 |
| 85 | 85 | 80 | 45 | 45 | 40 |
| 85 | 85 | 85 | 45 | 40 | 40 |
| 90 | 85 | 85 | 40 | 40 | 40 |
| 90 | 90 | 85 | 40 | 40 | 35 |
| 90 | 90 | 90 | 40 | 40 | 30 |
| 95 | 90 | 90 | 40 | 40 | 0 |
| 95 | 95 | 90 | 40 | 35 | 0 |
| 95 | 95 | 95 | 40 | 30 | 0 |
| 100 | 95 | 95 | 35 | 0 | 0 |
| 100 | 100 | 95 | 30 | 0 | 0 |
| 100 | 100 | 100 | 0 | 0 | 0 |

7.14.4 - Triple circuit – priority given to one circuit

| Loading sequence (%) | | | Unloading sequence (%) | | |
|----------------------|-------------|-------------|------------------------|-------------|-------------|
| Lead circ. | Lag circ. 1 | Lag circ. 2 | Lead circ. | Lag circ. 1 | Lag circ. 2 |
| 0 | 0 | 0 | 100 | 100 | 100 |
| 30 | 0 | 0 | 100 | 100 | 95 |
| 35 | 0 | 0 | 100 | 100 | 90 |
| 40 | 0 | 0 | 100 | 100 | 85 |
| 45 | 0 | 0 | 100 | 100 | 80 |
| 50 | 0 | 0 | 100 | 100 | 75 |
| 55 | 0 | 0 | 100 | 100 | 70 |
| 60 | 0 | 0 | 100 | 100 | 65 |
| 65 | 0 | 0 | 100 | 100 | 60 |
| 70 | 0 | 0 | 100 | 100 | 55 |
| 75 | 0 | 0 | 100 | 100 | 50 |
| 80 | 0 | 0 | 100 | 100 | 45 |
| 85 | 0 | 0 | 100 | 100 | 40 |
| 90 | 0 | 0 | 100 | 100 | 35 |
| 100 | 0 | 0 | 100 | 100 | 30 |
| 100 | 30 | 0 | 100 | 95 | 30 |
| 100 | 35 | 0 | 100 | 90 | 30 |
| 100 | 40 | 0 | 100 | 85 | 30 |
| 100 | 45 | 0 | 100 | 80 | 30 |
| 100 | 50 | 0 | 100 | 75 | 30 |
| 100 | 55 | 0 | 100 | 70 | 30 |
| 100 | 60 | 0 | 100 | 65 | 0 |
| 100 | 65 | 0 | 100 | 60 | 0 |
| 100 | 70 | 0 | 100 | 55 | 0 |
| 100 | 75 | 0 | 100 | 50 | 0 |
| 100 | 80 | 0 | 100 | 45 | 0 |
| 100 | 85 | 0 | 100 | 40 | 0 |
| 100 | 90 | 0 | 100 | 35 | 0 |
| 100 | 100 | 0 | 100 | 30 | 0 |
| 100 | 100 | 30 | 95 | 30 | 0 |
| 100 | 100 | 35 | 90 | 30 | 0 |
| 100 | 100 | 40 | 85 | 30 | 0 |
| 100 | 100 | 45 | 80 | 30 | 0 |
| 100 | 100 | 50 | 75 | 30 | 0 |
| 100 | 100 | 55 | 70 | 30 | 0 |
| 100 | 100 | 60 | 65 | 0 | 0 |
| 100 | 100 | 65 | 60 | 0 | 0 |
| 100 | 100 | 70 | 55 | 0 | 0 |
| 100 | 100 | 75 | 50 | 0 | 0 |
| 100 | 100 | 80 | 45 | 0 | 0 |
| 100 | 100 | 85 | 40 | 0 | 0 |
| 100 | 100 | 90 | 35 | 0 | 0 |
| 100 | 100 | 100 | 30 | 0 | 0 |
| | | | 0 | 0 | 0 |

7 - TOUCH PILOT CONTROL OPERATION

7.15 - Energy management module

The energy management module enables to control the level of energy consumption, providing users with information such as current unit status, compressors operating status, etc.

This option requires the installation of an additional SIOB board.

| Energy management option – board connections | | | | |
|--|--------------|-----------|-----------------|---|
| Description | Input/Output | Connector | Type | Remarks |
| Occupancy override control | DI-01 | J1 | Digital input | If the contact is closed in Remote mode, the unit goes into the occupied mode |
| Demand limit switch 2 | DI-02 | J1 | Digital input | If the contact is closed, the second capacity limit switch is active |
| Customer interlock | DI-03 | J1 | Digital input | Permits immediate unit shutdown (Remote mode only) |
| Ice storage | DI-04 | J1 | Digital input | If the contact is closed, the unit enters the ice storage mode |
| Space temperature | AI-01 | J25 | Analogue input | Active setpoint reset via space temperature control |
| Capacity limit control | AI-10 | J9 | Analogue input | Active setpoint reset via unit capacity control (4-20 mA) |
| Compressor A | DO-01 | J2 | Digital output | Output active if compressor A is operating |
| Compressor B | DO-02 | J2 | Digital output | Output active if compressor B is operating |
| Compressor C | DO-03 | J6 | Digital output | Output active if compressor C is operating |
| Chiller shutdown | DO-05 | J23 | Digital output | Output active (relay output) when the unit has completely stopped due to an alarm |
| Chiller in alert | DO-06 | J22 | Digital output | Output active (relay output) when the alert has been tripped |
| Unit capacity | A0-01 | J10 | Analogue output | 0 to10 VDC output |

7.16 - Master/slave assembly

Two units can be linked to create the master/slave assembly. The master unit can be controlled locally, remotely or by network commands. Master/slave assembly must be validated in order to start the master/slave chiller operation.

All control commands to the master/slave assembly (start/stop, setpoint selection, heating/cooling operation, load shedding, etc.) are handled by the unit which is configured as the master. The commands are transmitted automatically to the slave unit. If the master chiller is turned off while the master/slave function is active, then the slave chiller will be stopped. Under certain circumstances, the slave unit may be started first to balance the run times of the two units.

In the event of a communication failure between the two units, each unit will return to an autonomous operating mode until the fault is cleared. If the master unit is stopped due to an alarm, the slave unit is authorised to start.

NOTE: Master/slave assembly can be configured only by Carrier service.

7.17 - Heat reclaim option (30XA/30XB)

Air-conditioning system consumes a significant amount of energy that leaves the system in the form of wasted heat. Heat reclaim condenser water pump control enables to capture the energy and convert it into a useful heat source without decreasing the chiller plant capacity.

For air-cooled units fitted with water heat reclaim condenser, the option requires the installation of Reclaim SIOB board. The heat reclaim mode can be controlled locally with the Touch Pilot interface (RECLAIM – Reclaim mode), remotely with the user contact or by Network command.

The heat reclaim function is active when the heat reclaim entering water temperature is lower than the heat reclaim setpoint. The difference between the heat reclaim entering water temperature (RECLAIM menu) and the heat reclaim setpoint (SETPOINT menu) determines the number of circuits required to provide heat reclaim capacity.

Depending on the control mode, the Heat Reclaim option can be enabled as follows:

| Mode | Description |
|----------------|---|
| Local | Use the Touch Pilot user interface to set "Heat Reclaim Select" parameter to "yes" in the Reclaim menu (Main menu). |
| Remote | Close the RECL_SW input (DI-02, Reclaim SIOB board). |
| Network | Force the RECL_SW parameter to "yes" through the CCN bus (RECLAIM table). |

Units in Master/Slave assembly

When the unit is a Slave and operating in the Master/Slave assembly, the option is active depending on conditions given in the table below:

| Reclaim mode | Local mode (Heat Reclaim Select = yes) | Remote mode (RECL_SW) | Network mode (RECL_SEL CCN bus) |
|--------------|--|-----------------------|---------------------------------|
| no | no | open | no |
| yes | yes/no | closed | yes/no |
| yes | yes | open | yes/no |
| yes | yes/no | open | yes |

The heat reclaim function can be deactivated manually or automatically when the heat reclaim entering water temperature is higher than the heat reclaim setpoint, plus half of the heat reclaim deadband. In the deadband the heat reclaim function is still active.

Changeover procedure from cooling to heat reclaim mode:

- Start-up of the condenser pump.
- Verification of the condenser flow switch control contact. If this remains open after one minute of the condenser pump operation, the circuit remains in cooling mode and an alarm will be activated.
- As soon as delta between saturated condensing temperature and saturated suction temperature reaches 10°C, the pump-down sequence is activated.
- Pump down. Opening of the water condenser water inlet valve and closing of the air condenser air valve.
- The heat reclaim function starts after about three minutes

7.18 - Variable speed fans (option 17)

Air-cooled units fitted with the variable speed fans option allow for reducing the total unit consumption by adjusting the fan speed to the current operating conditions.

The control determines the optimum fan speed based on the current compressor capacity, outdoor air temperature, and leaving water temperature.

7.19 - Evaporator heater option (30XA/30XB)

The evaporator heater protects the evaporator against frost when the unit is stopped at low ambient air temperature. The heater is activated in the case of low outdoor air temperature conditions.

7 - TOUCH PILOT CONTROL OPERATION

7.20 - Free cooling option (30XA/30XB)

In air-cooled units only, this option allows for the direct use of low outdoor air temperature to cool the water circuit without activating the compressors.

The direct-expansion free cooling system uses the principle of the natural migration of the refrigerant from the evaporator to the condenser. The fans and a refrigerant pump ensure the transfer of the liquid refrigerant from the condenser to the evaporator, which accounts for low power consumption.

The free cooling option enables automatic operation as well as combined operation of mechanical cooling (compressor operation) and free cooling (FREECOOL – Free cooling). The control determines which circuit is allowed to run free cooling. Each refrigerant circuit can operate independently.

Cooling operation may be performed in the following combinations:

- two circuits in mechanical cooling
- two circuits in free cooling
- one circuit in mechanical cooling and one circuit in free cooling

The free cooling option is available for dual-circuit units. It requires the installation of SIOB board that controls the operation of the motorised mechanical changeover valves and the operation of the refrigerant pump.

Free cooling option is enabled based on the following criteria:

- The temperature difference between the outdoor air temperature and the controlled water temperature. The threshold can be configured by the user (GEN_CONF – General Configuration)
- The maximum operating time in free cooling (Full Load Timeout) when the water temperature setpoint is not reached (Full Load Timeout, GEN_CONF – General Configuration)

7.21 - Dry Cooler Free Cooling (30XB)

30XB units can be fitted with a dry cooler which thanks to the use of low outside air temperature facilitates the process of chilling water that is later used in the air-conditioning system (“dry cooler free cooling”). The dry cooler is used not only to assist in cooling water to meet the current cooling demand but it also allows for reducing energy consumption.

This “dry cooler free cooling” mode is enabled when the outside air temperature is below the water loop temperature and the service-configured start threshold parameter.

NOTE: Dry cooler water loop temperature and free cooling OAT measured by the control are read-only values that can be verified in the DC Free Cooling Status menu (DCFC_STA).

The control distinguishes between two types of fan control for a dry cooler free cooling option, where the first one embraces the use of fan staging and the second one that includes the use of variable speed fan. Mixed configuration can also be used (fixed and variable-speed fan control at the same time).

Free Cooling is normally stopped when the free cooling OAT is above the water loop temperature and the service-configured start/stop threshold. However, if it turns out that the cooling power of the dry cooler is not enough in order to reach the cooling setpoint, then the mechanical cooling will be started (when FC capacity is at 100%, then mechanical cooling can be started).

7.22 - Dry cooler option (30XW)

30XW units may come with the dry cooler option that enables the control of a Carrier dry cooler.

The chiller and the dry cooler have to be connected through a LEN RS-485.

7.23 - Hydronic kit option (30XA/30XB)

The hydronic kit option allows for continuous monitoring of the water flow rate.

Hydronic kit option provides the following parameters:

- Inlet and outlet water pressure (PUMPSTAT in the Main menu)
- Evaporator flow rate
- Evaporator capacity

The water flow rate is based on the pressure difference between the evaporator inlet and outlet pressures and the evaporator pressure drop curves.

The evaporator capacity is calculated according to the flow rate, the water constant, and the difference between the entering and leaving evaporator water temperature.

7.24 - 30XA-ZE and 30XW-ZE units (HFO)

The Touch Pilot system may also control air-cooled and water-cooled units with R-1234ze refrigerant (HFO).

Please note that this option comes with advanced electrical box fan protection. In the case of the electrical box fan failure, the unit is shut down and alarm 10100 is triggered.

7.25 - High condensing temperature option (30XW)

7.25.1 - R134a configuration

For water-cooled units only, the economizer enables the increase of the maximum condensing threshold. This means that the saturated condensing temperature can reach a maximum of 63°C (145°F) compared with a maximum of 50°C (122°F) for units that are not fitted with this option.

7.25.2 - HFO configuration

For HFO units (30XW units with R-1234ze refrigerant), the high condensing option authorizes the saturated condensing temperature to reach a maximum of 70°C (158°F) compared with a maximum of 55°C (131°F) for units that are not fitted with this option.

7.26 - Maximum condenser leaving water temperature option (30XW)

For water-cooled units only, this option allows the user to limit the condenser leaving water temperature to 45°C (113°F) and enables to limit the current absorbed by the compressor. When the condensing temperature reaches 44°C (111°F), the increase in the compressor loading is stopped. When the temperature exceeds 45°C (113°F), the compressor is unloaded.

7 - TOUCH PILOT CONTROL OPERATION

7.27 - Time schedule function

The Touch Pilot system control includes two time schedules.

The first schedule (schedule 1 OCCPC01S) allows for the automatic changeover of the unit from occupied to unoccupied mode: the unit is started during occupied periods.

The second schedule (schedule 2 OCCPC02S) allows for the automatic change of the active setpoint from occupied to unoccupied setpoint, provided that the Auto mode has been selected (RESETCFG – Reset Configuration).

7.27.1 - Occupied/unoccupied periods

- Cooling/heating setpoint 1 is active during occupied periods.
- Cooling/heating setpoint 2 is active during unoccupied periods.

Each schedule consists of eight user-configurable periods. Each period can be validated as active or inactive for each day of the week as well as for a given holiday period. The day begins at 00:00 and ends at 23:59.

The schedule is in unoccupied mode unless a time period is active. If two periods coincide or they are active on the same day, priority is given to the occupied period. Time schedule can be modified by the user in the Configuration menu (see also section 4.11).

7.27.2 - Holidays

This function is used to define 16 holiday periods. Each period is defined by three parameters: the month, the start day and the duration of the holiday period.

During the holiday periods the controller will be in occupied or unoccupied mode, depending on the periods validated as holidays. Each holiday period can be modified by the user (see also section 6.4).

NOTE: The broadcast function (BROADCASTS) must be activated in order to use the holiday schedule.

7.28 - Black box function


Touch Pilot registers the values of about 20 predefined variables every 5 seconds. If an operation alarm is raised, the control saves a data set of 180 registrations (including 168 records preceding the alarm and 12 following the alarm) for a duration of 15 minutes of the unit operation.


Each registration is associated with a time schedule defined in hours, minutes and seconds. The control can store the maximum of 20 data sets in the memory. If the threshold of 20 data sets is reached, a rotary registration mechanism is triggered (the old data set is replaced with the new data set).

NOTE: Former data sets can be recovered only by Carrier service.

7.29 - Trending

This function enables to visualise the operations of the unit.

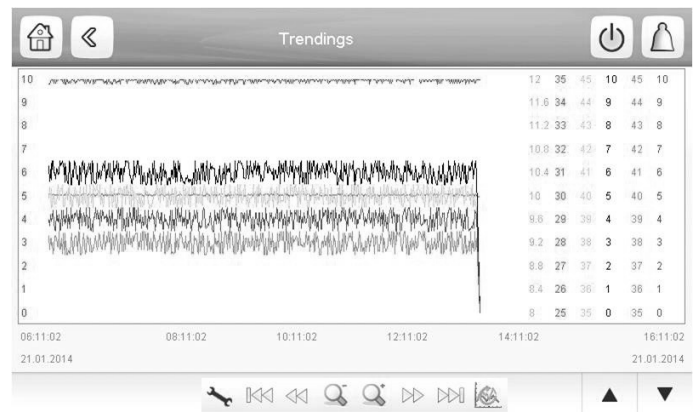
To access the Trending menu, navigate to the Main menu and select **Trendings** 

Select the parameters to be visualised and press .

Go to the visualization screen by pressing the **Up/Down** buttons.



| Parameter | Unit | Value | Setpoint 1 | Setpoint 2 |
|--|------|-------|------------|------------|
| <input checked="" type="checkbox"/> COOL_LWT | °C | 0 | 0.0 | 10.0 |
| <input checked="" type="checkbox"/> COOL_EWT | °C | 0 | 8.0 | 12.0 |
| <input type="checkbox"/> COND_LWT | °C | * | -17.8 | -6.4 |
| <input type="checkbox"/> COND_EWT | °C | * | -17.8 | -9.2 |
| <input checked="" type="checkbox"/> OAT | °C | 0 | 25.0 | 35.0 |
| <input checked="" type="checkbox"/> SCT_A | °C | 0 | 35.0 | 45.0 |
| <input checked="" type="checkbox"/> SST_A | °C | 0 | 0.0 | 10.0 |
| <input checked="" type="checkbox"/> SCT_B | °C | 0 | 35.0 | 45.0 |
| <input checked="" type="checkbox"/> SST_B | °C | 0 | 0.0 | 10.0 |
| <input type="checkbox"/> SCT_C | °C | * | -17.8 | -6.3 |



8 - DIAGNOSTICS – TROUBLESHOOTING

The control system has many fault tracing aid functions, protecting the unit against risks that could result in the failure of the unit. The local interface gives quick access to monitor all unit operating conditions. If an operating fault is detected, the alarm is triggered.

8.1 - E-mail notifications

The control provides the option to define one or two recipients who receive e-mail notifications each time the new alarm occurs or all existing alarms have been reset.

NOTE: E-mail notifications can be configured only by Carrier service.

8.2 - Displaying alarms



The control allows the quick display of the unit status. When the alarm is activated, the bell on the touch screen lights up.

- The blinking bell icon indicates that there is an alarm, but the unit is still running.
- The highlighted bell icon indicates that the unit is shut down due to a detected fault.

8.3 - Current alarms

The Current alarms view provides a list of currently active alarms, including the date and time the alarm occurred. The control displays up to 10 current alarms.

To access the Current alarms view, press the **Alarm** button



 in the upper-right part of the screen, and then select **Current Alarms** 

8.4 - Resetting alarms

Touch Pilot control distinguishes between two types of alarms:

- General alarms are used to indicate pumps failure, transducers faults, network connection problems, etc.
- Major alarms are used to indicate process failure.

The alarm can be reset either automatically or manually via the Reset alarms menu. The Reset alarms menu displays up to five alarm codes which are currently active on the unit. Only logged-in users can access the menu (see also section 4.6).

To access the Reset alarms menu, press the **Alarm** button  and select **Reset Alarms** 

The alarm can be reset without stopping the machine. In the event of a power supply interrupt, the unit restarts automatically without the need for an external command. However, any faults active when the supply is interrupted are saved and may in certain cases prevent a circuit or a unit from restarting. Once the cause of the alarm has been identified and corrected, it will be displayed in the alarm history.

8.5 - Alarm history

Information regarding resolved alarms is stored in the Alarm history menu which is divided into 50 recent alarms and 50 recent major alarms. Alarm history can be accessed through the Touch Pilot user interface or the Network Service Tool.

To access the Alarm history menu, press the **Alarm** button

 and select **Alarm History** 

8 - DIAGNOSTICS – TROUBLESHOOTING

8.6 - Alarm codes

The alarm codes are displayed in the Reset Alarms menu, while in the Current Alarm menu and alarm histories textual information regarding the event is provided.

8.6.1 - General alarm codes

| No. | Code | Alarm description | Reset type | Action taken | Possible cause |
|---------------------------|-------|---|--|---|--|
| THERMISTOR FAILURE | | | | | |
| 1 | 15001 | Evaporator entering water thermistor fault | Automatic, if thermistor reading returns to normal | Unit shuts down | Defective thermistor |
| 2 | 15002 | Evaporator leaving water thermistor fault | As above | Unit shuts down | As above |
| 3 | 15050 | Cooler Leaving Fluid #2 Thermistor | As above | Unit shuts down | As above |
| 4 | 15003 | Defrost thermistor fault, circuit A | As above | Cooling mode: Alert is displayed Heating mode: Circuit A shuts down | As above |
| 5 | 15004 | Defrost thermistor fault, circuit B | As above | Cooling mode: Alert is displayed Heating mode: Circuit B shuts down | As above |
| 6 | 15006 | Condenser entering water thermistor fault | As above | Heating mode: Unit shuts down | As above |
| 7 | 15007 | Condenser leaving water thermistor fault | As above | As above | As above |
| 8 | 15008 | Reclaim condenser entering thermistor fault, circuit A | As above | Unit returns to the air-cooled mode | As above |
| 9 | 15009 | Reclaim condenser leaving thermistor fault, circuit B | As above | As above | As above |
| 10 | 15010 | OAT thermistor fault | As above | Unit shuts down | As above |
| 11 | 15011 | Master/slave common water thermistor fault | As above | Master/slave operation is disabled and the unit returns to the stand-alone mode | As above |
| 12 | 15032 | MASTER/Slave Common Heat Fluid Thermistor | As above | As above | As above |
| 13 | 15012 | Suction gas thermistor fault, circuit A | As above | Circuit A shuts down | As above |
| 14 | 15013 | Suction gas thermistor fault, circuit B | As above | Circuit B shuts down | As above |
| 15 | 15014 | Suction gas thermistor fault, circuit C | As above | Circuit C shuts down | As above |
| 16 | 15015 | Discharge gas thermistor fault, circuit A | As above | Circuit A shuts down | As above |
| 17 | 15016 | Discharge gas thermistor fault, circuit B | As above | Circuit B shuts down | As above |
| 18 | 15017 | Discharge gas thermistor fault, circuit C | As above | Circuit C shuts down | As above |
| 19 | 15036 | Dry Cooler Leaving thermistor failure | As above | None | As above |
| 20 | 15046 | Free Cooling Water Loop Thermistor Failure | As above | Dry cooler free cooling disabled | As above |
| 21 | 15047 | Free Cooling Leaving Water Thermistor Failure | As above | Dry cooler free cooling disabled | As above |
| 22 | 15048 | Free Cooling OAT Thermistor Failure | As above | Dry cooler free cooling disabled | As above |
| 23 | 15018 | Condenser subcooling liquid thermistor fault, circuit A | As above | Unit returns to the air-cooled mode | As above |
| 24 | 15019 | Condenser subcooling liquid thermistor fault, circuit B | As above | As above | As above |
| 25 | 15021 | Space temperature thermistor fault | As above | None | As above |
| 26 | 15023 | Evaporator heater feedback thermistor fault | As above | None | As above |
| 27 | 15024 | Economizer gas thermistor fault, circuit A | As above | Economizer function disabled | As above |
| 28 | 15025 | Economizer gas thermistor fault, circuit B | As above | As above | As above |
| 29 | 15026 | Economizer gas thermistor fault, circuit C | As above | As above | As above |
| 30 | 15030 | Free cooling liquid thermistor fault, circuit A | As above | Free cooling disabled | As above |
| 31 | 15031 | Free cooling liquid thermistor fault, circuit B | As above | As above | As above |
| TRANSDUCER FAILURE | | | | | |
| 32 | 12001 | Discharge transducer fault, circuit A | Automatic, if sensor voltage reading returns to normal | Circuit A shuts down | Defective transducer or installation fault |
| 33 | 12002 | Discharge transducer fault, circuit B | As above | Circuit B shuts down | As above |
| 34 | 12003 | Discharge transducer fault, circuit C | As above | Circuit C shuts down | As above |
| 35 | 12004 | Suction transducer fault, circuit A | As above | Circuit A shuts down | As above |
| 36 | 12005 | Suction transducer fault, circuit B | As above | Circuit B shuts down | As above |
| 37 | 12006 | Suction transducer fault, circuit C | As above | Circuit C shuts down | As above |
| 38 | 12007 | Heat reclaim pump-down pressure transducer fault, circuit A | As above | Reclaim session stopped and the unit returns to the air-cooled mode | As above |
| 39 | 12008 | Heat reclaim pump-down pressure transducer fault, circuit B | As above | As above | As above |
| 40 | 12010 | Oil pressure transducer fault, circuit A | As above | Circuit A shuts down | As above |
| 41 | 12011 | Oil pressure transducer fault, circuit B | As above | Circuit B shuts down | As above |
| 42 | 12012 | Oil pressure transducer fault, circuit C | As above | Circuit C shuts down | As above |
| 43 | 12013 | Economizer pressure transducer fault, circuit A | As above | Circuit A shuts down | As above |
| 44 | 12014 | Economizer pressure transducer fault, circuit B | As above | Circuit B shuts down | As above |
| 45 | 12015 | Economizer pressure transducer fault, circuit C | As above | Circuit C shuts down | As above |

8 - DIAGNOSTICS – TROUBLESHOOTING

| No. | Code | Alarm description | Reset type | Action taken | Possible cause |
|-----|-------|---|------------|--|--|
| 46 | 12016 | Free cooling pump inlet pressure transducer fault, circuit A | As above | Free cooling stopped and the unit returns to mechanical cooling | As above |
| 47 | 12017 | Free cooling pump outlet pressure transducer fault, circuit A | As above | As above | As above |
| 48 | 12018 | Free cooling pump inlet pressure transducer fault, circuit B | As above | As above | As above |
| 49 | 12019 | Free cooling pump outlet pressure transducer fault, circuit B | As above | As above | As above |
| 50 | 12022 | Circuit A Heatpump Approach Pressure Transducer | As above | Cooler pinch control disabled in Cooling mode; discharge superheat control is required | As above |
| 51 | 12023 | Circuit B Heatpump Approach Pressure Transducer | As above | As above | As above |
| 52 | 12024 | Water pressure 1 transducer failure (before the evaporator) | As above | Alert - the values read by the hydronic kit function are not reliable | As above |
| 53 | 12025 | Water pressure 2 transducer failure (after the evaporator) | As above | As above | As above |
| 54 | 12026 | Water pressure 3 transducer failure (before the filter) | As above | As above | As above |
| 55 | 12027 | Water pressure 4 transducer failure (after the filter) | As above | As above | As above |
| 57 | 12029 | Low water pressure | As above | Alert – the unit continues to operate | Water loop pressure too low, risk of pump cavitation |

COMMUNICATION FAILURE

| | | | | | |
|----|------|---|---|---|---|
| 59 | 4101 | Communication loss with Compressor Board A | Automatic, if communication is re-established | Unit shuts down | Bus installation fault or defective board |
| 60 | 4201 | Communication loss with Compressor Board B | As above | Unit shuts down | As above |
| 61 | 4301 | Communication loss with Compressor Board C | As above | Unit shuts down | As above |
| 62 | 4901 | Communication loss with SIOB Board Number 1 | As above | Unit shuts down | As above |
| 63 | 4902 | Communication loss with SIOB Board Number 2 | As above | Unit shuts down | As above |
| 64 | 4903 | Communication loss with SIOB Board Number 3 | As above | Unit shuts down | As above |
| 65 | 4904 | Communication loss with SIOB Board Number 4 | As above | Unit shuts down | As above |
| 66 | 4905 | Communication loss with SIOB Board Number 5 | As above | Unit shuts down | As above |
| 67 | 4906 | Communication loss with SIOB Board Number 6 | As above | Unit shuts down | As above |
| 68 | 4501 | Communication loss with Fan Board Number 1 | As above | Circuit A shuts down | As above |
| 69 | 4502 | Communication loss with Fan Board Number 2 | As above | Circuit B shuts down | As above |
| 70 | 4503 | Communication loss with Fan Board Number 3 | As above | Circuit C shuts down | As above |
| 71 | 4504 | Loss of Communication with Auxiliary # 4 (Dry Cooler Free Cooling Option) | As above | Dry cooler free cooling disabled and the unit returns to mechanical cooling | As above |
| 72 | 4505 | Loss of Communication with Auxiliary # 3 Dry cooler Option | As above | Dry cooler mode is stopped | As above |
| 73 | 4801 | Communication loss with VLT Board Number 1, (units w/o option 17) | As above | Circuit A shuts down | As above |
| 74 | 4802 | Communication loss with VLT Board Number 2, (units w/o option 17) | As above | Circuit B shuts down | As above |
| 75 | 4803 | Communication loss with VLT Board Number 3, (units w/o option 17) | As above | Circuit C shuts down | As above |
| 76 | 4704 | Loss of communication with Fan VLT Drive Board A1 (option 17) | As above | Circuit A shuts down | As above |
| 77 | 4705 | Loss of communication with Fan VLT Drive Board A2 (option 17) | As above | Circuit A shuts down | As above |
| 78 | 4706 | Loss of communication with Fan VLT Drive Board A3 (option 17) | As above | Circuit A shuts down | As above |
| 79 | 4707 | Loss of communication with Fan VLT Drive Board B1 (option 17) | As above | Circuit B shuts down | As above |
| 80 | 4708 | Loss of communication with Fan VLT Drive Board B2 (option 17) | As above | Circuit B shuts down | As above |
| 81 | 4709 | Loss of communication with Fan VLT Drive Board B3 (option 17) | As above | Circuit B shuts down | As above |

PROCESS FAILURE

| | | | | | |
|----|-------|---------------------------------------|---|--|--|
| 85 | 10001 | Evaporator frost protection | Manual | Unit shuts down, but the pump continues to run | No water flow, defective thermistor |
| 86 | 10002 | Condenser frost protection, circuit A | Automatic (if saturated discharge temperature is more than 4.4°C) or Manual | Circuit A shuts down, but the pump is running | Discharge pressure transducer defective, refrigerant leak or low condenser water temperature |
| 87 | 10003 | Condenser frost protection, circuit B | As above | Circuit B shuts down, but the pump is running | As above |
| 88 | 10004 | Condenser frost protection, circuit C | As above | Circuit C shuts down, but the pump is running | As above |

8 - DIAGNOSTICS – TROUBLESHOOTING

| No. | Code | Alarm description | Reset type | Action taken | Possible cause |
|-----|-------|---|---|---|---|
| 89 | 10005 | Low suction temperature, circuit A | Automatic (the first alarm in the last 24 hours) or Manual | Circuit A shuts down | Pressure sensor defective, EXV blocked or lack of refrigerant |
| 90 | 10006 | Low suction temperature, circuit B | As above | Circuit B shuts down | As above |
| 91 | 10007 | Low suction temperature, circuit C | As above | Circuit C shuts down | As above |
| 92 | 10008 | High superheat, circuit A | Manual | Circuit A shuts down | As above |
| 93 | 10009 | High superheat, circuit B | Manual | Circuit B shuts down | As above |
| 94 | 10010 | High superheat, circuit C | Manual | Circuit C shuts down | As above |
| 95 | 10011 | Low superheat, circuit A | Manual | Circuit A shuts down | As above |
| 96 | 10012 | Low superheat, circuit B | Manual | Circuit B shuts down | As above |
| 97 | 10013 | Low superheat, circuit C | Manual | Circuit C shuts down | As above |
| 98 | 10014 | Customer safety loop failure | Automatic (the first alarm in the last 24 hours) or Manual | Unit shuts down | Customer interlock closed |
| 99 | 10028 | Electrical box thermostat | Automatic | Unit shuts down | Electrical box fault: Control box poorly ventilated or poor electrical connection |
| 100 | 10029 | System manager communication fault | Automatic, if communication is re-established | Unit returns to the stand-alone mode | CCN bus installation defective |
| 101 | 10030 | Master/slave communication failure | Automatic | Master/slave control disabled | As above |
| 102 | 10067 | Low oil pressure, circuit A | Manual | Circuit A shuts down | Pressure sensor fault, defective wiring or oil filter installation fault |
| 103 | 10068 | Low oil pressure, circuit B | Manual | Circuit B shuts down | As above |
| 104 | 10069 | Low oil pressure, circuit C | Manual | Circuit C shuts down | As above |
| 105 | 10070 | Maximum oil filter differential pressure, circuit A | Manual | The affected compressor is stopped, other compressors continue to run | As above |
| 106 | 10071 | Maximum oil filter differential pressure, circuit B | Manual | As above | As above |
| 107 | 10072 | Maximum oil filter differential pressure, circuit C | Manual | As above | As above |
| 108 | 10084 | High oil filter drop pressure, circuit A | Manual | None | Pressure sensor fault, wiring defective, oil filter installation fault |
| 109 | 10085 | High oil filter drop pressure, circuit B | Manual | None | As above |
| 110 | 10086 | High oil filter drop pressure, circuit C | Manual | None | As above |
| 111 | 10075 | Low oil level, circuit A | Automatic (three alarms in the last 24 hours) or Manual | Circuit A shuts down | Oil level too low or oil level detector defective |
| 112 | 10076 | Low oil level, circuit B | As above | Circuit B shuts down | As above |
| 113 | 10077 | Low oil level, circuit C | As above | Circuit C shuts down | As above |
| 117 | 10031 | Emergency stop | Automatic | Unit shuts down | Network emergency stop command |
| 118 | 10032 | Evaporator pump 1 fault | Manual | Unit is restarted with another pump running. If no pumps are available, the unit shuts down | Pump overheats or poor pump connection |
| 119 | 10033 | Evaporator pump 2 fault | Manual | As above | As above |
| 120 | 10015 | Flow controller fault - condenser flow switch failure | Automatic (the first alarm in the last 24 hours) or Manual | Condenser pump is stopped | Condenser flow switch open |
| 121 | 10034 | Reclaim operation failure, circuit A | Manual | Circuit A returns to the air-cooled mode | Low condenser flow |
| 122 | 10035 | Reclaim operation failure, circuit B | Manual | Circuit B returns to the air-cooled mode | As above |
| 123 | 10037 | High condensing temperature, circuit A | Automatic | Circuit A shuts down | Defective transducer |
| 124 | 10038 | High condensing temperature, circuit B | Automatic | Circuit B shuts down | As above |
| 125 | 10039 | High condensing temperature, circuit C | Automatic | Circuit C shuts down | As above |
| 129 | 10043 | Low entering water temperature in heating | Automatic, if EWT returns to normal or Heating mode is disabled | None | Entering water temperature is below 3.3°C |
| 130 | 10073 | Condenser pump 1 fault | Manual | Unit is restarted with another pump running. If no pumps are available, the unit shuts down | Pump overheats or poor pump connection |
| 131 | 10074 | Condenser pump 2 fault (not available!) | Manual | As above | As above |

8 - DIAGNOSTICS – TROUBLESHOOTING

| No. | Code | Alarm description | Reset type | Action taken | Possible cause |
|-----|-------|--|--|--|---|
| 132 | 10078 | High discharge gas temperature, circuit A | Manual | Circuit A shuts down | Defective transducer, max. condensing temperature setpoint too low or refrigerant charge too high |
| 133 | 10079 | High discharge gas temperature, circuit B | Manual | Circuit B shuts down | As above |
| 134 | 10080 | High discharge gas temperature, circuit C | Manual | Circuit C shuts down | As above |
| 135 | 10081 | Suction valve closed, circuit A | Manual | Circuit A shuts down | Economizer pressure transducer defective, suction valve fault |
| 136 | 10082 | Suction valve closed, circuit B | Manual | Circuit B shuts down | As above |
| 137 | 10083 | Suction valve closed, circuit C | Manual | Circuit C shuts down | As above |
| 138 | 10087 | Slide valve control unverifiable, circuit A | Manual | None | Defective or incorrectly wired solenoid valves, defective current transformer |
| 139 | 10088 | Slide valve control unverifiable, circuit B | Manual | None | As above |
| 140 | 10089 | Slide valve control unverifiable, circuit C | Manual | None | As above |
| 141 | 10090 | Flow controller configuration fault | Manual | Unit is not allowed to restart | Defective flow controller or wiring error |
| 142 | 10091 | Flow controller fault – evaporator flow switch failure | Automatic (the first alarm in the last 24 hours) or Manual | Compressors and the evaporator pump are stopped | As above |
| 143 | 10100 | Electrical box fan failure (units with HFO only) | Manual | Unit shuts down | Electrical box fan malfunction or fan current probe malfunction |
| 144 | 10094 | Free cooling operation failure, circuit A | Automatic (three alarms in the last 24 hours) or Manual | Circuit A shuts down, Free cooling can be started 30 minutes later | Refrigerant pump fault |
| 145 | 10095 | Free cooling operation failure, circuit B | As above | Circuit B shuts down, Free cooling can be started 30 minutes later | As above |
| 146 | 10097 | Water exchanger temperature sensors swapped | Manual | Unit shuts down | Leaving water temperature is higher than entering water temperature |
| 180 | 10050 | Refrigerant Leakage Detection | Manual | None | Refrigerant leak or leak detector defective |
| 181 | 10101 | Free Cooling Process Failure | Automatic, if free cooling conditions return to normal | Dry cooler free cooling stopped and the unit returns to mechanical cooling | Conditions not suitable for dry cooler free cooling |

MAINTENANCE ALARMS

| | | | | | |
|-----|----------------|--|--------|------|--|
| 147 | 13- <i>nnn</i> | Service maintenance alert | Manual | None | Preventive maintenance date has passed |
| 182 | 13005 | Fgas check needed, call your maintenance company | Manual | None | As above |

VLT DRIVE FAILURE

| | | | | | |
|-----|----------------|--|-----------|----------------------|--|
| 148 | 20- <i>nnn</i> | Variable speed controller error, circuit A (units w/o option 17) | Manual | Circuit A shuts down | Speed controller fault (see section 8.6.2) |
| 149 | 23- <i>nnn</i> | Variable speed controller error, circuit B (units w/o option 17) | Manual | Circuit B shuts down | As above |
| 150 | 26- <i>nnn</i> | Variable speed controller error, circuit C (units w/o option 17) | Manual | Circuit C shuts down | As above |
| 151 | 20- <i>nnn</i> | VLT Fan Drive A1 Failure (option 17) | Manual | Circuit A shuts down | As above |
| 152 | 21- <i>nnn</i> | VLT Fan Drive A2 Failure (option 17) | Manual | Circuit A shuts down | As above |
| 153 | 22- <i>nnn</i> | VLT Fan Drive A3 Failure (option 17) | Manual | Circuit A shuts down | As above |
| 154 | 23- <i>nnn</i> | VLT Fan Drive B1 Failure (option 17) | Manual | Circuit B shuts down | As above |
| 155 | 24- <i>nnn</i> | VLT Fan Drive B2 Failure (option 17) | Manual | Circuit B shuts down | As above |
| 156 | 25- <i>nnn</i> | VLT Fan Drive B3 Failure (option 17) | Manual | Circuit B shuts down | As above |
| 160 | 38- <i>nnn</i> | Variable speed controller alert, circuit A (units w/o option 17) | Manual | None | Speed controller alert (see section 8.6.2) |
| 161 | 41- <i>nnn</i> | Variable speed controller alert, circuit B (units w/o option 17) | Manual | None | As above |
| 162 | 44- <i>nnn</i> | Variable speed controller alert, circuit C (units w/o option 17) | Manual | None | As above |
| 163 | 38- <i>nnn</i> | Variable speed controller A1 alert (option 17) | Automatic | None | As above |
| 164 | 39- <i>nnn</i> | Variable speed controller A2 alert (option 17) | Automatic | None | As above |
| 165 | 40- <i>nnn</i> | Variable speed controller A3 alert (option 17) | Automatic | None | As above |

8 - DIAGNOSTICS – TROUBLESHOOTING

| No. | Code | Alarm description | Reset type | Action taken | Possible cause |
|------------------------------|--------|--|--|-------------------------------|---|
| 166 | 41-nnn | Variable speed controller B1 alert (option 17) | Automatic | None | As above |
| 167 | 42-nnn | Variable speed controller B2 alert (option 17) | Automatic | None | As above |
| 168 | 43-nnn | Variable speed controller B3 alert (option 17) | Automatic | None | As above |
| EXV FAILURE | | | | | |
| 174 | 57020 | Main EXV stepper motor Failure - cir A | Manual | Circuit A shuts down | Stepper motor failure |
| 175 | 57021 | Main EXV stepper motor Failure - cir B | Manual | Circuit B shuts down | As above |
| 176 | 57022 | Main EXV stepper motor Failure - cir C | Manual | Circuit C shuts down | As above |
| 177 | 57023 | EXV eco stepper motor Failure - cir A | Manual | Circuit A shuts down | As above |
| 178 | 57024 | EXV eco stepper motor Failure - cir B | Manual | Circuit B shuts down | As above |
| 179 | 57025 | EXV eco stepper motor Failure - cir C | Manual | Circuit C shuts down | As above |
| COMPRESSOR FAILURE | | | | | |
| 183-201 | 11nn | Compressor A fault | Manual | Unit shuts down | See section 8.6.3 |
| 202-220 | 21nn | Compressor B fault | Manual | Unit shuts down | As above |
| 221-239 | 31nn | Compressor C fault | Manual | Unit shuts down | As above |
| SOFTWARE FAILURE | | | | | |
| 172 | 55001 | Database module fault | Automatic | Unit shuts down | Software problem. Contact Carrier Service |
| 173 | 56001 | Lenscan module fault | Automatic | Unit shuts down | Software problem. Contact Carrier Service |
| CONFIGURATION FAILURE | | | | | |
| 114 | 9001 | Master chiller configuration error Number #1 to nn | Automatic, if master/slave configuration returns to normal | Master/Slave control disabled | Incorrect unit configuration |
| 115 | 8000 | Initial factory configuration required | Automatic, if configuration is made | Unit not allowed to start | Factory configuration required |
| 116 | 7001 | Illegal factory configuration | Automatic, if configuration is corrected | Unit not allowed to start | Incorrect unit configuration |

8.6.2 - Drive alarms

The tables below present the most common alarms associated with the variator malfunction. Please refer to the applicable Danfoss documentation for more information on other alarms.

| Code | Alarm /Alert | Description | Action to be taken |
|-------------------------------|--------------|--------------------------------|--|
| Variator alarms (-nnn) | | | |
| 2 | Alarm | Live zero fault | Contact Carrier Service |
| 4 | Alarm | Mains phase loss | Check the VFD supply voltage and the phase balance ($\pm 3\%$) |
| 7 | Alarm | Overvoltage | Contact Carrier Service |
| 8 | Alarm | Undervoltage | Contact Carrier Service |
| 9 | Alarm | Inverter overloaded | Check the VFD output current |
| 10 | Alarm | Motor overtemperature | Check the motor temperature |
| 11 | Alarm | Motor thermistor | Contact Carrier Service |
| 12 | Alarm | Torque limit exceeded | Check the VFD output current |
| 13 | Alarm | Overcurrent | Check the VFD output current |
| 14 | Alarm | Earth fault | Check if an earth fault exists |
| 16 | Alarm | Motor short-circuit | Check if there is a short-circuit at the VFD terminals |
| 17 | Alarm | Serial communication timeout | Check the connections and the shielding of the serial communication cable |
| 23* | Alarm | Internal fan fault | Check the internal fan rotation |
| 25 | Alarm | Brake resistor short-circuited | Contact Carrier Service |
| 26 | Alarm | Brake resistor power limit | Contact Carrier Service |
| 28 | Alarm | Brake verification | Contact Carrier Service |
| 29 | Alarm | VFD temperature too high | Space temperature too high or VFD ventilation obstructed or damaged |
| 30 | Alarm | Motor phase U missing | Check wiring of phase U |
| 31 | Alarm | Motor phase V missing | Check wiring of phase V |
| 32 | Alarm | Motor phase W missing | Check wiring of phase W |
| 33 | Alarm | Inrush fault | Current demand too high: Let the VFD cool down for 20 minutes before starting it again |
| 34 | Alarm | Fieldbus communication fault | Check the connections and the shielding of the serial communication cable |
| 36 | Alarm | Mains failure | Check the VFD supply voltage and the phase balance ($\pm 3\%$) |
| 38 | Alarm | Internal fault | Contact Carrier Service |

8 - DIAGNOSTICS – TROUBLESHOOTING

| Code | Alarm /Alert | Description | Action to be taken |
|-------------------------------|--------------|------------------------------------|---|
| 47 | Alarm | 24 V supply low | Contact Carrier Service |
| 48 | Alarm | 1.8 V supply low | Contact Carrier Service |
| 57** | Alarm | AMA timeout | Contact Carrier Service |
| 65 | Alarm | Control board overtemperature | Check the space temperature and the VFD fan |
| 67 | Alarm | Option configuration has changed | Contact Carrier Service |
| 68 | Alarm | Emergency stop | Contact Carrier Service |
| 71 | Alarm | PTC 1 emergency stop | Contact Carrier Service |
| 72 | Alarm | Emergency stop | Contact Carrier Service |
| 80 | Alarm | Drive initialized to default value | Contact Carrier Service |
| 94 | Alarm | End of curve | Contact Carrier Service |
| 95 | Alarm | Torque loss | Contact Carrier Service |
| 243 | Alarm | IGBT defective | Contact Carrier Service |
| 251*** | Alarm | New parts detached | Contact Carrier Service |
| Variator alerts (-nnn) | | | |
| 1 | Alert | 10 V low | Contact Carrier Service |
| 2 | Alert | Live zero error | Contact Carrier Service |
| 3 | Alert | No motor | Check the motor connections |
| 4 | Alert | Mains phase loss | Check the VFD supply voltage and the phase balance ($\pm 3\%$) |
| 5 | Alert | DC link voltage high | Check the VFD supply voltage and the phase balance ($\pm 3\%$) |
| 6 | Alert | DC link voltage low | Check the VFD supply voltage and the phase balance ($\pm 3\%$) |
| 7 | Alert | DC overvoltage | Contact Carrier Service |
| 8 | Alert | DC undervoltage | Contact Carrier Service |
| 9 | Alert | Inverter overloaded | Check the VFD output current |
| 10 | Alert | Motor overtemperature | Check the motor temperature |
| 11 | Alert | Motor thermistor | Contact Carrier Service |
| 12 | Alert | Torque limit exceeded | Check the VFD output current |
| 13 | Alert | Overcurrent | Check the VFD output current |
| 14 | Alert | Earth fault | Check if an earth fault exists |
| 17 | Alert | Control word timeout | Check the connections and the shielding of the serial communication cable |
| 23*** | Alert | Internal fan fault | Check the internal fan rotation |
| 25 | Alert | Brake resistor short-circuited | Contact Carrier Service |
| 26 | Alert | Brake resistor power limit | Contact Carrier Service |
| 28 | Alert | Brake verification | Contact Carrier Service |
| 34 | Alert | Fieldbus communication fault | Check the connections and the shielding of the serial communication cable |
| 36 | Alert | Mains failure | Check the VFD supply voltage and the phase balance ($\pm 3\%$) |
| 47 | Alert | 24 V supply low | Contact Carrier Service |
| 49 | Alert | Motor speed limit exceeded | Contact Carrier Service |
| 59 | Alert | Current limit exceeded | Check the VFD output current |
| 62 | Alert | Output frequency at maximum limit | Check the VFD output current |
| 64 | Alert | Voltage limit | Supply voltage too low |
| 65 | Alert | Control board overtemperature | Check the space temperature and the VFD fan |
| 66 | Alert | Heat sink temperature low | Space temperature too low |
| 71 | Alert | PTC1 emergency stop | Contact Carrier Service |
| 72 | Alert | Emergency stop | Contact Carrier Service |
| 90† | Alert | Encoder loss | Contact Carrier Service |
| 94 | Alert | End of curve | Contact Carrier Service |
| 95 | Alert | Torque loss | Contact Carrier Service |
| 96 | Alert | Start delayed | Contact Carrier Service |
| 97 | Alert | Stop delayed | Contact Carrier Service |
| 98 | Alert | Clock fault | Contact Carrier Service |
| 243 | Alert | IGBT defective | Contact Carrier Service |
| 247 | Alert | Capacity board temperature | Contact Carrier Service |

* Error 24 and 104 possible

** Error 50 to 58 possible

***Error 70 or 250 possible

† Not applicable to variator size 102

8 - DIAGNOSTICS – TROUBLESHOOTING

8.6.3 - Compressor alarms

| Alarm code* | Description | Reset type | Possible cause |
|-------------|--|------------|---|
| XX-01 | Motor temperature too high | Manual | Motor/wiring fault |
| XX-02 | Motor temperature outside the range | Manual | Probe defective or incorrect wiring |
| XX-03 | Motor temperature outside the range | Manual | Coil fouled, lack of condenser flow, condenser valve blocked, fan circuit fault, high entering air or condenser water temperature |
| XX-04 | Current consumption too high | Manual | - |
| XX-05 | Locked rotor | Manual | Mechanical compressor fault, motor fault or defective compressor slide valve |
| XX-06 | Phase L1 lost | Manual | Power supply wiring fault |
| XX-07 | Phase L2 lost | Manual | As above |
| XX-08 | Phase L3 lost | Manual | As above |
| XX-09 | Low current alarm | Manual | Defective contactor or capacity fault |
| XX-10 | Current increase fault during the star-delta passage | Manual | Incorrect wiring or no power for the delta contactor |
| XX-11 | Contactor fault | Manual | Incorrect wiring or defective contactor or TCPM board |
| XX-12 | Motor stop impossible | Manual | Incorrect wiring or defective contactor |
| XX-13 | Phase reversal | Manual | - |
| XX-14 | MTA configuration fault | Manual | MTA configuration incorrect or defective TCPM board |
| XX-15 | Incorrect configuration switch | Manual | Configuration switch S1 incorrect wiring or defective TCPM board |
| XX-16 | Switch modification detected | Manual | As above |
| XX-17 | Power supply cut during operation | Automatic | Verify that power supply cuts have occurred |
| XX-18 | Critical software error (UL 1998) | Manual | Power network noise or defective TCPM board |
| XX-19 | Critical error on two current parameters (UL 1998) | Manual | Power network noise or defective TCPM board |

*XX stands for compressor (11 – compressor A, 21 – compressor B, 31 - compressor C)



Order No.: 13453, 03.2018. Supersedes order No.: 13453, 10.2017.

Manufacturer reserves the right to change any product specifications without notice.

Manufactured by: Carrier SCS, Montluel, France.
Printed in the European Union.



Quality and Environment
Management Systems
Approval